

Combo Module-40C4

COMS-40C4

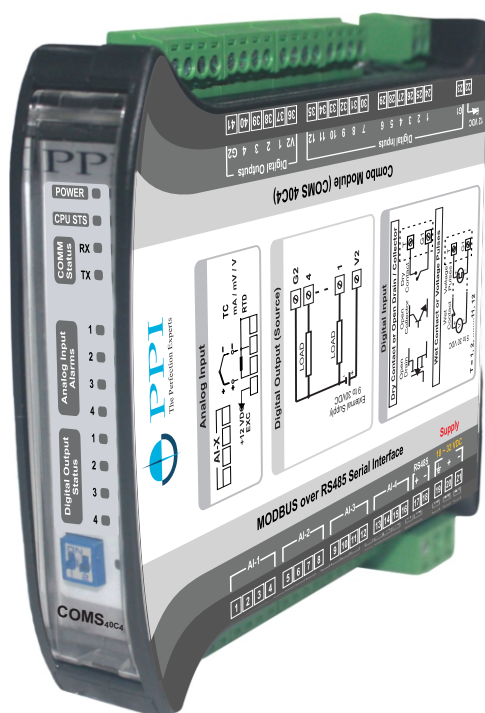
4 AI + 12 DI + 4 DO
DIN-Rail Mount
MODBUS over Serial
18~32 VDC Operated

Process Precision Instruments

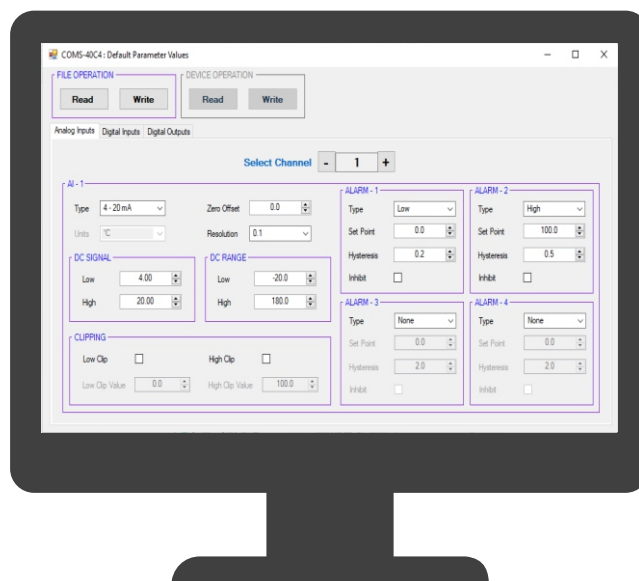
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User Manual



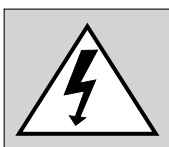
Configuration Tool



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Section 1 ELECTRICAL CONNECTIONS

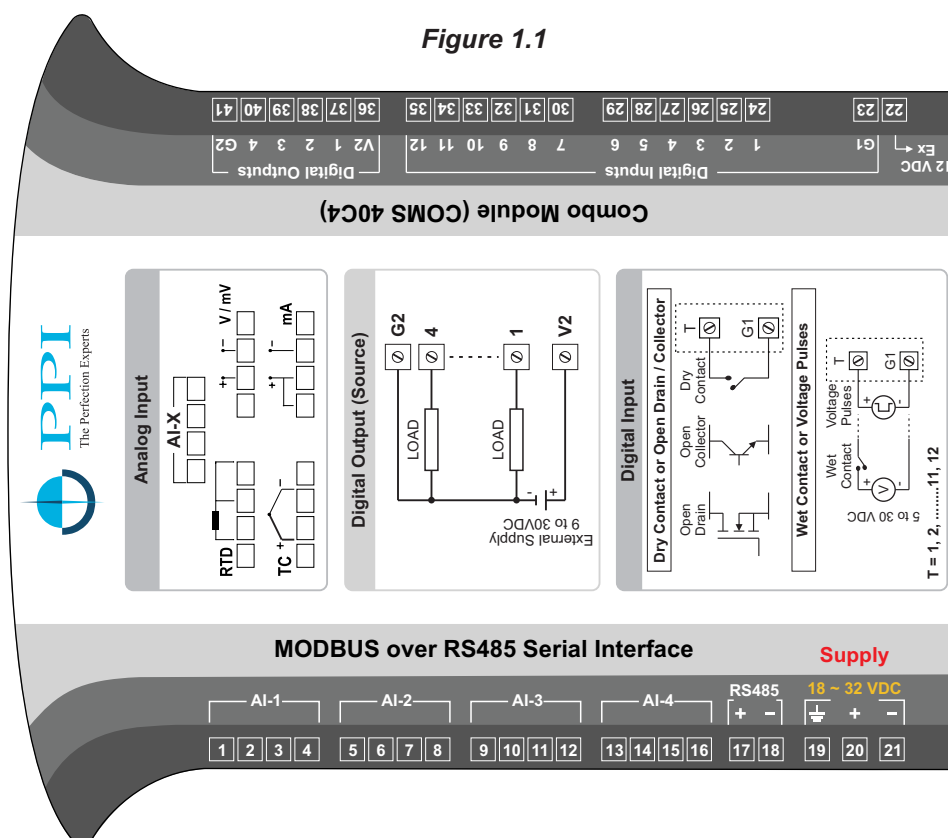


WARNING
MISHANDLING / NEGLIGENCE CAN RESULT
IN PERSONAL DEATH OR SERIOUS INJURY.

1. The user must rigidly observe the Local Electrical Regulations.
2. Do not make any connections to the unused terminals for making a tie-point for other wires (or for any other reasons) as they may have some internal connections. Failing to observe this may result in permanent damage to the indicator.
3. Run power supply cables separated from the low-level signal cables (like RTD, Thermocouples, DC Linear Current / Voltage etc.). If the cables are run through conduits, use separate conduits for power supply cable and low-level signal cables.
4. Use appropriate fuses and switches, wherever necessary, for driving the high voltage loads to protect the module from any possible damage due to high voltage surges of extended duration or short-circuits on loads.
5. Take care not to over-tighten the terminal screws while making connections.
6. Make sure that the module supply is switched-off while making/removing any connections.

CONNECTION DIAGRAM

The Figure 1.1 illustrates Electrical Connection Diagrams.



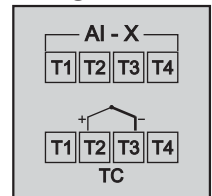
ANALOG INPUT CHANNELS

Each of the 4 input channels are identical from wiring connection viewpoint. For explanation purpose, the 4 terminals pertaining to each channel have been marked as T1, T2, T3 & T4 in the following pages. The descriptions below apply to all the channels with no deviations.

Thermocouple

Connect Thermocouple Positive (+) to terminal T2 and Negative (-) to terminal T3 as shown in **Figure 1.2**. Use the correct type of Thermocouple extension lead wires or compensating cable for the entire distance ensuring the correct polarity throughout. Avoid joints in the cable.

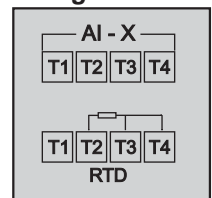
Figure 1.2



RTD Pt100, 3-wire

Connect single lead end of **RTD** bulb to terminal T2 and the double leaded ends to terminals T3 and T4 (interchangeable) as shown in **Figure 1.3**. Use copper conductor leads of very low resistance ensuring that all 3 leads are of the same gauge and length. Avoid joints in the cable.

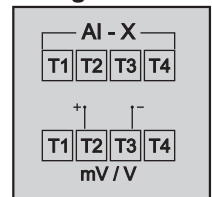
Figure 1.3



DC Linear Voltage (mV / V)

Use a shielded twisted pair with the shield grounded at the signal source for connecting mV / V source. Connect common (-) to terminal T3 and the signal (+) to terminal T2, as shown in **Figure 1.4**.

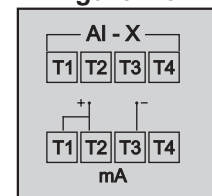
Figure 1.4



DC Linear Current (mA)

Use a shielded twisted pair with the shield grounded at the signal source for connecting mA source. Connect common (-) to terminal T3 and the signal (+) to terminal T2. Also **short** terminals T1 & T2. Refer **Figure 1.5**.

Figure 1.5



DIGITAL INPUT CHANNELS

The 12 Digital Input Channels can be programmed to accept one of the followings :

- (a) Dry Contact **or** Potential-Free Contacts / Open Drain / Open Collector
- (b) 5 to 30 VDC Wet Contact / Voltage Pulses

Each of the 12 digital input channels are identical from wiring connection viewpoint. The figures below apply to all the channels with no deviations.

Figure 1.6 (a)

Dry Contact **or** Open Drain / Collector

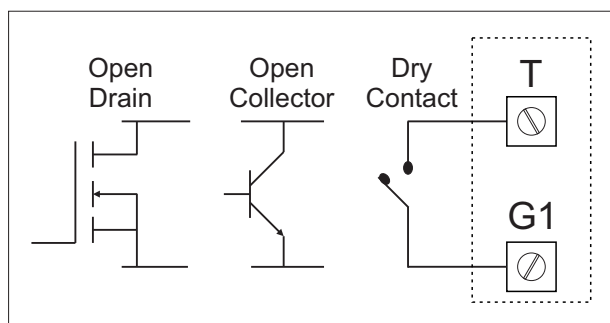
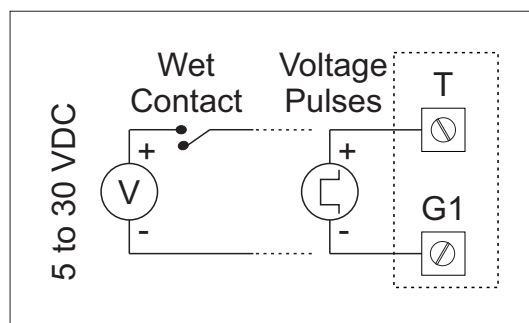


Figure 1.6 (b)

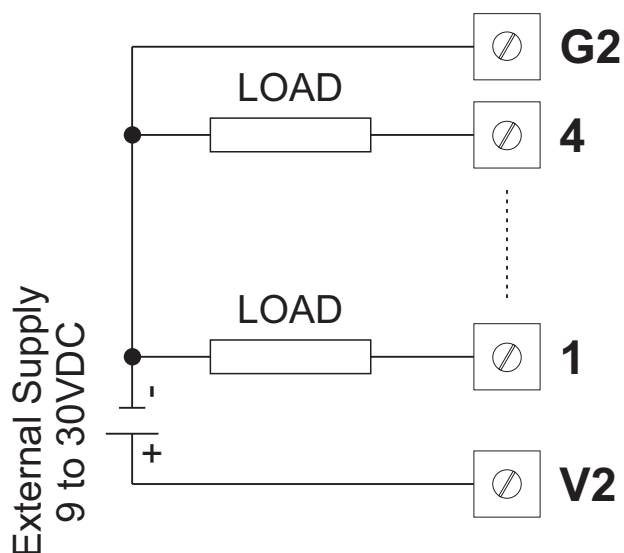
Wet Contact **or** Voltage Pulses



T = 1, 2,11, 12

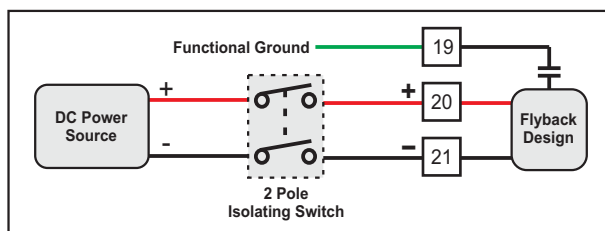
DIGITAL OUTPUT CHANNELS

The Digital Outputs are Source type. Each of the 4 output channels are identical from a wiring connection viewpoint.



POWER SUPPLY (Terminals 20, 21)

Figure 1.7



As standard, the Module is supplied with power connections suited for 18 to 32 VDC power source. The accuracy / performance of the Module is not affected by the variations in the supply within specified limits of 18 to 32 VDC. Use well-insulated copper conductor wire of the size not smaller than 0.5mm² for power supply connections ensuring proper polarity as shown in Figure 1.7. The Module is not provided with fuse and power switch. If necessary, mount them separately. Use a slow blow fuse rated for 0.5A current.

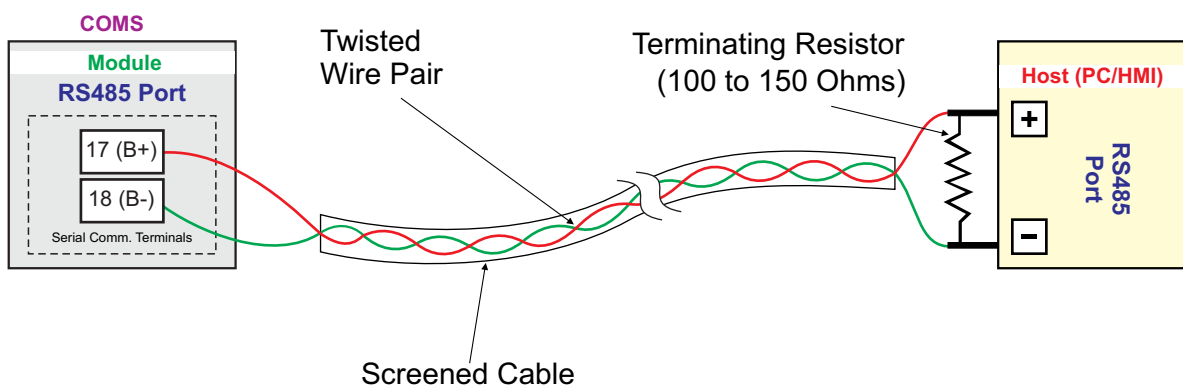
For safety and enhanced electrical noise immunity, it is highly recommended to connect Main Power Supply 'Earth' to terminal 19.

SERIAL COMMUNICATION PORT

The wiring connections for interfacing the Host (PC/HMI) with COMS is shown in the figure 1.8.

For reliable noise free communication, use a pair of twisted wires inside screened cable. The wire should have less than 100 ohms / km nominal DC resistance (Typically 24 AWG or thicker). Connect the terminating resistor (Typically 100 to 150 ohm) at one end to improve noise immunity.

Figure 1.8



Note

In case of non-availability of RS485 port on Host PC, use appropriate **Serial Protocol Converter** to match the available serial port on the host like USB to RS485 and RS232 to RS485 (Refer few images below). Please ensure that the appropriate **Device Driver** for the selected converter is installed on the Host PC.



RS232 to RS485



USB to RS485

Section 2

ANALOG INPUT PARAMETERS

The Table 2.1 describes Input Registers (Read only parameters) and Table 2.2 describes Holding Registers (Read/Write Parameters), respectively. The MODBUS addresses are also specified.

Table 2.1 : Input Registers (Read-Only Parameters)

Parameter Description	MODBUS Address	Values													
Process Value (Note 1) Measured Temperature (in °C / °F) for Thermocouple / RTD inputs or Scaled Counts for DC Volts / mA inputs. Note : The Process Values are also available in 32-Bit Single Precision Float format. Refer Appendix-C.	1561 (AI-1) to 1564 (AI-4)	Signed integer values from -30000 to +30000 representing the measured process values. Refer Table 2.3 for the various input types and the corresponding measured ranges. The following constant counts indicate PV Errors. <table><tr><th>Value</th><th>PV Error Type</th></tr><tr><td>-32768</td><td>Under Range</td></tr><tr><td>+32752</td><td>Over Range</td></tr><tr><td>+32767</td><td>Sensor Open</td></tr></table>	Value	PV Error Type	-32768	Under Range	+32752	Over Range	+32767	Sensor Open					
Value	PV Error Type														
-32768	Under Range														
+32752	Over Range														
+32767	Sensor Open														
Alarm-1 Status	1577	Refer Appendix-D for accessing the Alarm Status as Discrete Inputs / Coils. <table><tr><td>Bit 15</td><td>- - - -</td><td>Bit 3</td><td>Bit 2</td><td>Bit 1</td><td>Bit 0</td><td>(X = 1, 2, 3, 4)</td></tr></table> Ignore Bit-4 to Bit-15 <table><tr><th>Bit Value</th><th>Status</th></tr><tr><td>0</td><td>Alarm OFF</td></tr><tr><td>1</td><td>Alarm ON</td></tr></table>	Bit 15	- - - -	Bit 3	Bit 2	Bit 1	Bit 0	(X = 1, 2, 3, 4)	Bit Value	Status	0	Alarm OFF	1	Alarm ON
Bit 15	- - - -		Bit 3	Bit 2	Bit 1	Bit 0	(X = 1, 2, 3, 4)								
Bit Value	Status														
0	Alarm OFF														
1	Alarm ON														
Alarm-2 Status	1578														
Alarm-3 Status	1579														
Alarm-4 Status	1580														
Digital Filter	1612 (AI-1) to 1615 (AI-4)	0 to 90% (Default : 0%)													
Ambient Temperature	82	Signed integer values from -30000 to +30000 representing the measured Ambient Temperature through the semi-conductor sensor mounted on the Module. The measured value is always in °C with 0.1 resolution. For example, 30.0°C is represented as 300.													

Table 2.2 : Holding Registers (Read/Write Parameters)

Parameter Description	MODBUS Address	Settings (Default Value)																																				
Input Type Select Input type in accordance with the type of Thermocouple or RTD sensor or transducer output connected for process value measurement.	83 (AI-1) to 86 (AI-4)	<table><tr><th>Value</th><th>Type</th></tr><tr><td>0</td><td>Type J Thermocouple</td></tr><tr><td>1</td><td>Type K Thermocouple</td></tr><tr><td>2</td><td>Type T Thermocouple</td></tr><tr><td>3</td><td>Type R Thermocouple</td></tr><tr><td>4</td><td>Type S Thermocouple</td></tr><tr><td>5</td><td>Type B Thermocouple</td></tr><tr><td>6</td><td>Type N Thermocouple</td></tr><tr><td>7</td><td>Type E Thermocouple</td></tr><tr><td>8</td><td>RTD Pt100, 3-wire</td></tr><tr><td>9</td><td>0 to 20 mA</td></tr><tr><td>10</td><td>4 to 20 mA</td></tr><tr><td>11</td><td>0 to 80 mV</td></tr><tr><td>12</td><td>Reserved (Default: 0 to 80 mV)</td></tr><tr><td>13</td><td>0 to 1.25 V</td></tr><tr><td>14</td><td>0 to 5 V</td></tr><tr><td>15</td><td>0 to 10 V</td></tr><tr><td>16</td><td>1 to 5 V</td></tr></table> (Default : 0 to 10 V)	Value	Type	0	Type J Thermocouple	1	Type K Thermocouple	2	Type T Thermocouple	3	Type R Thermocouple	4	Type S Thermocouple	5	Type B Thermocouple	6	Type N Thermocouple	7	Type E Thermocouple	8	RTD Pt100, 3-wire	9	0 to 20 mA	10	4 to 20 mA	11	0 to 80 mV	12	Reserved (Default: 0 to 80 mV)	13	0 to 1.25 V	14	0 to 5 V	15	0 to 10 V	16	1 to 5 V
Value	Type																																					
0	Type J Thermocouple																																					
1	Type K Thermocouple																																					
2	Type T Thermocouple																																					
3	Type R Thermocouple																																					
4	Type S Thermocouple																																					
5	Type B Thermocouple																																					
6	Type N Thermocouple																																					
7	Type E Thermocouple																																					
8	RTD Pt100, 3-wire																																					
9	0 to 20 mA																																					
10	4 to 20 mA																																					
11	0 to 80 mV																																					
12	Reserved (Default: 0 to 80 mV)																																					
13	0 to 1.25 V																																					
14	0 to 5 V																																					
15	0 to 10 V																																					
16	1 to 5 V																																					
Temperature Units <i>(Applicable only for Thermocouples & RTD Pt100 Inputs)</i> Selects temperature measurement units in °C or °F.	99 (AI-1) to 102 (AI-4)	Conditional Parameter <i>(Note2)</i> <table><tr><th>Value</th><th>Unit</th></tr><tr><td>0</td><td>°C</td></tr><tr><td>1</td><td>°F</td></tr></table> (Default : °C)	Value	Unit	0	°C	1	°F																														
Value	Unit																																					
0	°C																																					
1	°F																																					
DC Resolution <i>(Note1)</i> <i>(Applicable only for mA/mV/V Inputs)</i> This parameter value should be used in conjunction with the process value for interpretation of decimal place. For example if the value for this parameter is 0.01 then the measured process value of 3000 should be interpreted as 30.00.	115 (AI-1) to 118 (AI-4)	Conditional Parameter <i>(Note2)</i> <table><tr><th>Value</th><th>Resolution</th></tr><tr><td>0</td><td>1</td></tr><tr><td>1</td><td>0.1</td></tr><tr><td>2</td><td>0.01</td></tr><tr><td>3</td><td>0.001</td></tr><tr><td>4</td><td>0.0001</td></tr></table> (Default : 1 Unit for DC Linear input & 0.1 for Thermocouple & RTD)	Value	Resolution	0	1	1	0.1	2	0.01	3	0.001	4	0.0001																								
Value	Resolution																																					
0	1																																					
1	0.1																																					
2	0.01																																					
3	0.001																																					
4	0.0001																																					

Parameter Description	MODBUS Address	Settings (Default Value)																								
Signal Low <i>(Applicable only for mA/mV/V Inputs)</i> The transmitter output signal value corresponding to Range Low process value. Refer Appendix-A : DC Linear Signal Interface for details. Note : The value should be set as integer counts ignoring decimal value. For e.g. 4.00 mA should be set as 400 counts.	501 (AI-1) to 504 (AI-4)	Conditional Parameter ^(Note2) <table border="1"> <thead> <tr> <th>Input Type</th><th>Settings</th><th>Default</th></tr> </thead> <tbody> <tr> <td>0 to 20 mA</td><td>0.00 to Signal High</td><td>0.00</td></tr> <tr> <td>4 to 20 mA</td><td>4.00 to Signal High</td><td>4.00</td></tr> <tr> <td>0 to 80 mV</td><td>0.00 to Signal High</td><td>0.00</td></tr> <tr> <td>0 to 1.25 V</td><td>0.000 to Signal High</td><td>0.000</td></tr> <tr> <td>0 to 5 V</td><td>0.000 to Signal High</td><td>0.000</td></tr> <tr> <td>0 to 10 V</td><td>0.00 to Signal High</td><td>0.00</td></tr> <tr> <td>1 to 5 V</td><td>1.000 to Signal High</td><td>1.000</td></tr> </tbody> </table>	Input Type	Settings	Default	0 to 20 mA	0.00 to Signal High	0.00	4 to 20 mA	4.00 to Signal High	4.00	0 to 80 mV	0.00 to Signal High	0.00	0 to 1.25 V	0.000 to Signal High	0.000	0 to 5 V	0.000 to Signal High	0.000	0 to 10 V	0.00 to Signal High	0.00	1 to 5 V	1.000 to Signal High	1.000
Input Type	Settings	Default																								
0 to 20 mA	0.00 to Signal High	0.00																								
4 to 20 mA	4.00 to Signal High	4.00																								
0 to 80 mV	0.00 to Signal High	0.00																								
0 to 1.25 V	0.000 to Signal High	0.000																								
0 to 5 V	0.000 to Signal High	0.000																								
0 to 10 V	0.00 to Signal High	0.00																								
1 to 5 V	1.000 to Signal High	1.000																								
Signal High <i>(Applicable only for mA/mV/V Inputs)</i> The transmitter output signal value corresponding to Range High process value. Refer Appendix-A : DC Linear Signal Interface for details. Note : The value should be set as integer counts ignoring decimal value. For e.g. 80.00 mV should be set as 8000 counts.	517 (AI-1) to 520 (AI-4)	Conditional Parameter ^(Note2) <table border="1"> <thead> <tr> <th>Input Type</th><th>Settings</th><th>Default</th></tr> </thead> <tbody> <tr> <td>0 to 20 mA</td><td>Signal Low to 20.00</td><td>20.00</td></tr> <tr> <td>4 to 20 mA</td><td>Signal Low to 20.00</td><td>20.00</td></tr> <tr> <td>0 to 80 mV</td><td>Signal Low to 80.00</td><td>80.00</td></tr> <tr> <td>0 to 1.25 V</td><td>Signal Low to 1.250</td><td>1.250</td></tr> <tr> <td>0 to 5 V</td><td>Signal Low to 5.000</td><td>5.000</td></tr> <tr> <td>0 to 10 V</td><td>Signal Low to 10.00</td><td>10.00</td></tr> <tr> <td>1 to 5 V</td><td>Signal Low to 5.000</td><td>5.000</td></tr> </tbody> </table>	Input Type	Settings	Default	0 to 20 mA	Signal Low to 20.00	20.00	4 to 20 mA	Signal Low to 20.00	20.00	0 to 80 mV	Signal Low to 80.00	80.00	0 to 1.25 V	Signal Low to 1.250	1.250	0 to 5 V	Signal Low to 5.000	5.000	0 to 10 V	Signal Low to 10.00	10.00	1 to 5 V	Signal Low to 5.000	5.000
Input Type	Settings	Default																								
0 to 20 mA	Signal Low to 20.00	20.00																								
4 to 20 mA	Signal Low to 20.00	20.00																								
0 to 80 mV	Signal Low to 80.00	80.00																								
0 to 1.25 V	Signal Low to 1.250	1.250																								
0 to 5 V	Signal Low to 5.000	5.000																								
0 to 10 V	Signal Low to 10.00	10.00																								
1 to 5 V	Signal Low to 5.000	5.000																								
Range Low <i>(Applicable only for mA/mV/V Inputs)</i> The process value corresponding to the Signal Low value from the transmitter. Refer Appendix-A : DC Linear Signal Interface for details.	131 (AI-1) to 134 (AI-4)	Conditional Parameter ^(Note2) -30000 to 30000 (Default : 0)																								
Range High <i>(Applicable only for mA/mV/V Inputs)</i> The process value corresponding to the Signal High value from the transmitter. Refer Appendix-A : DC Linear Signal Interface for details.	147 (AI-1) to 150 (AI-4)	Conditional Parameter ^(Note2) -30000 to 30000 (Default : 1000)																								
Offset for PV ^(Note1) This value is algebraically added to the measured PV to derive the final PV. Final PV = Measured PV + Offset	163 (AI-1) to 166 (AI-4)	-30000 to 30000 (Default : 0)																								

Parameter Description	MODBUS Address	Settings (Default Value)								
Alarm-1 Type Refer Alarm-4 Type	179 (AI-1) to 182 (AI-4)	<table><tr><th>Value</th><th>Type</th></tr><tr><td>0</td><td>None</td></tr><tr><td>1</td><td>Process Low</td></tr><tr><td>2</td><td>Process High</td></tr></table> (Default : None)	Value	Type	0	None	1	Process Low	2	Process High
Value	Type									
0	None									
1	Process Low									
2	Process High									
Alarm-2 Type Refer Alarm-4 Type	243 (AI-1) to 246 (AI-4)									
Alarm-3 Type Refer Alarm-4 Type	307 (AI-1) to 310 (AI-4)									
Alarm-4 Type <i>None</i> The Alarm function is disabled. <i>Process Low</i> The Alarm is activated upon the PV equaling or falling below the ‘Alarm Set-point’ value. <i>Process High</i> The Alarm is activated upon the PV equaling or rising above the ‘Alarm Set-point’ value.	371 (AI-1) to 374 (AI-4)									
Alarm-1 Set-point <i>(Note 1)</i> Refer Alarm-4 Set-point	195 (AI-1) to 198 (AI-4)	Min. to Max. Range specified for the selected Input Type Refer Table 2.3 (Default : Min or Max Range depending on the Alarm type)								
Alarm-2 Set-point <i>(Note 1)</i> Refer Alarm-4 Set-point	259 (AI-1) to 262 (AI-4)									
Alarm-3 Set-point <i>(Note 1)</i> Refer Alarm-4 Set-point	323 (AI-1) to 326 (AI-4)									
Alarm-4 Set-point <i>(Note 1)</i> Sets limit for Process-High or Process-Low Alarm.	387 (AI-1) to 390 (AI-4)									

Parameter Description	MODBUS Address	Settings (Default Value)						
Alarm-1 Hysteresis (Note 1) Refer Alarm-4 Hysteresis	211 (AI-1) to 214 (AI-4)	1 to 30000 (Default : 20)						
Alarm-2 Hysteresis (Note 1) Refer Alarm-4 Hysteresis	275 (AI-1) to 278 (AI-4)							
Alarm-3 Hysteresis (Note 1) Refer Alarm-4 Hysteresis	339 (AI-1) to 342 (AI-4)							
Alarm-4 Hysteresis (Note 1) Sets differential (dead) band between Alarm switching ON and OFF states.	403 (AI-1) to 406 (AI-4)							
Alarm-1 Inhibit Refer Alarm-4 Inhibit	227 (AI-1) to 230 (AI-4)	<table><tr><th>Value</th><th>Inhibit</th></tr><tr><td>0</td><td>Disable</td></tr><tr><td>1</td><td>Enable</td></tr></table> (Default : Disable)	Value	Inhibit	0	Disable	1	Enable
Value	Inhibit							
0	Disable							
1	Enable							
Alarm-2 Inhibit Refer Alarm-4 Inhibit	291 (AI-1) to 294 (AI-4)							
Alarm-3 Inhibit Refer Alarm-4 Inhibit	355 (AI-1) to 358 (AI-4)							
Alarm-4 Inhibit <i>Enable</i> The Alarm activation is suppressed until the PV is within Alarm limits from the time the Module is Powered-on. This allows suppressing the Alarm during the start-up Alarm conditions. <i>Disable</i> The Alarm is not suppressed during the start-up Alarm conditions.	419 (AI-1) to 422 (AI-4)							

Parameter Description	MODBUS Address	Settings (Default Value)						
Enable Bottom Clipping <i>(Applicable only for mA / mV / V Inputs)</i> Refer Appendix-B.	435 (AI-1) to 438 (AI-4)	<table><tr><th>Value</th><th>Enable</th></tr><tr><td>0</td><td>No</td></tr><tr><td>1</td><td>Yes</td></tr></table> (Default : No)	Value	Enable	0	No	1	Yes
Value	Enable							
0	No							
1	Yes							
Bottom Clip Value <i>(Applicable only for mA / mV / V Inputs)</i> Refer Appendix-B.	451(AI-1) to 454 (AI-4)	-30000 to 30000 (Default : 0)						
Enable Top Clipping <i>(Applicable only for mA / mV / V Inputs)</i> Refer Appendix-B.	467 (AI-1) to 470 (AI-4)	<table><tr><th>Value</th><th>Enable</th></tr><tr><td>0</td><td>No</td></tr><tr><td>1</td><td>Yes</td></tr></table> (Default : No)	Value	Enable	0	No	1	Yes
Value	Enable							
0	No							
1	Yes							
Top Clip Value <i>(Applicable only for mA / mV / V Inputs)</i> Refer Appendix-B.	483 (AI-1) to 486 (AI-4)	-30000 to 30000 (Default : 1000)						

Note 1

Thermocouples (J, K, T, R, S, B, N, E) and RTD Pt100 (3-wire) Inputs

The process value is always measured in 0.1°C/°F resolution. That is, for example, the value 300 means 30.0°C / °F.

The same should be followed while setting the values for the parameters that are resolution based (like Zero Offset, Alarm Set-point, Alarm Hysteresis, etc.). That is for example, set 300 counts for 30.0°C / °F.

DC mA/mV/V Inputs

(Also Refer Appendix A : DC Linear Signal Interface)

The measured PV is a Resolution-less Scaled Value derived using the values for the parameters : Signal Low, Signal High, Range Low and Range High. The parameter 'DC Resolution' holds the desired resolution that can be used to insert *appropriate Decimal Place* in the scaled PV. For example, if the DC Resolution value is 2 (0.01) then the scaled value of 3000 can be read as 30.00.

Similarly the corresponding parameters like Zero Offset, Alarm Set-point, Alarm Hysteresis, etc., are also resolution less and, if desired, the parameter value for 'DC Resolution' should be used for *appropriate Decimal Place*.

Note 2

Conditional Parameters are those whose usage depend upon the values set for some other parameters. For example; the parameters 'Signal Low' & 'Signal High' for a selected channel are used only if the input type for the selected channel is DC Input (mA/ mV / V). The access to the conditional parameters for Read / Write operation, however, is not restricted.

Table 2.3

Input Type	Range (Min. to Max.)	Resolution
Type J Thermocouple	0 to +960.0°C / +32.0 to +1760.0°F	0.1 °C / °F
Type K Thermocouple	-200.0 to +1376.0°C / -328.0 to +2508.0°F	
Type T Thermocouple	-200.0 to +387.0°C / -328.0 to +728.0°F	
Type R Thermocouple	0 to +1771.0°C / +32.0 to +3219.0°F	
Type S Thermocouple	0 to +1768.0°C / +32.0 to +3214.0°F	
Type B Thermocouple	0 to +1826.0°C / +32.0 to +3318.0°F	
Type N Thermocouple	0 to +1314.0°C / +32.0 to +2397.0°F	
Type E Thermocouple	-200 to +1000.0°C / -328.0 to +1832.0°F	
3-wire, RTD Pt100	-199.0 to +850.0°C / -328.0 to +1562.0°F	
0 to 20mA DC current	-30000 to 30000 units	1
4 to 20mA DC current		0.1
0 to 80mV DC voltage		0.01
0 to 1.25V DC voltage		0.001
0 to 5.0V DC voltage		0.0001
0 to 10.0V DC voltage		Units
1 to 5.0V DC voltage		



Section 3

DIGITAL INPUT PARAMETERS

For user convenience, most parameters are accessible both as Bit-Mapped Modbus Registers & Discrete Inputs / Coils.

1. Select Digital Input Type

This parameter selects all the eight 12 inputs as one of the followings :

- (a) Dry Contact **or** Potential-Free Contacts / Open Drain / Open Collector
- (b) 5 to 30 VDC Wet Contact / Voltage Pulses

Table 3.1
Configuration Parameter (Stored in Non-Volatile memory)

Modbus Data Type	MODBUS Address	Values						
Holding Register Function Code (0x06 & 0x10)	2033	<table><tr><th>Value</th><th>DI Type</th></tr><tr><td>0</td><td>Dry (Potential-Free) Open / Close Contact or Open Drain / Collector (Sink)</td></tr><tr><td>1</td><td>Wet Open / Close Contact or Voltage Pulses</td></tr></table> Default : Dry (Potential-Free) Open / Close Contact or Open Drain / Collector (Sink)	Value	DI Type	0	Dry (Potential-Free) Open / Close Contact or Open Drain / Collector (Sink)	1	Wet Open / Close Contact or Voltage Pulses
Value	DI Type							
0	Dry (Potential-Free) Open / Close Contact or Open Drain / Collector (Sink)							
1	Wet Open / Close Contact or Voltage Pulses							

2. Instantaneous Digital Input Status (Read-Only Parameters)

These parameters reflect the current DI Status at the time of reading the Bit-Mapped Modbus Register / Coils.

Table 3.2
Run Time Parameter (Read Only)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Input or Holding Register Function Code (0x03 or 0x04)	38	<table><tr><td>Bit 15</td><td>. . .</td><td>Bit 11</td><td>. . .</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-12 to Bit-15 DI-1 Status DI-2 Status ⋮ DI-12 Status <table><tr><th>Bit Value</th><th>DI Status</th></tr><tr><td>0</td><td>Contact Open / Logic Low</td></tr><tr><td>1</td><td>Contact Close / Logic High</td></tr></table>	Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0	Bit Value	DI Status	0	Contact Open / Logic Low	1	Contact Close / Logic High
Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0									
Bit Value	DI Status													
0	Contact Open / Logic Low													
1	Contact Close / Logic High													
Discrete Input (Coils) Function Code (0x01 & 0x02)	1 (DI-1) to 12 (DI-12)	<table><tr><th>Coil Value</th><th>DI Status</th></tr><tr><td>0</td><td>Contact Open / Logic Low</td></tr><tr><td>1</td><td>Contact Close / Logic High</td></tr></table>	Coil Value	DI Status	0	Contact Open / Logic Low	1	Contact Close / Logic High						
Coil Value	DI Status													
0	Contact Open / Logic Low													
1	Contact Close / Logic High													

3 (a). Low-to-High Latched Digital Input Status (Read-Only Parameters)

This parameter value is set to 1 upon detecting the change in status from 'Open-to-Close' for a Dry / Wet Contact Closure input or from 'Low-to-High' logic level for PNP / NPN Sensor Input. This value is latched until acknowledged by writing to 'Low-to-High Acknowledge Command' Register / Coil.

Table 3.3
Run Time Parameter (Read Only)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Input or Holding Register <i>Function Code (0x03 or 0x04)</i>	40	<table><tr><td>Bit 15</td><td>. . .</td><td>Bit 11</td><td>. . .</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-12 to Bit-15 DI-1 Low-to-High Latched Status DI-2 Low-to-High Latched Status ... DI-12 Low-to-High Latched Status <table><tr><th>Bit Value</th><th>DI Status</th></tr><tr><td>0</td><td>No 'Low-to-High' Transition</td></tr><tr><td>1</td><td>'Low-to-High' Transition Detected</td></tr></table>	Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0	Bit Value	DI Status	0	No 'Low-to-High' Transition	1	'Low-to-High' Transition Detected
Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0									
Bit Value	DI Status													
0	No 'Low-to-High' Transition													
1	'Low-to-High' Transition Detected													
Discrete Input (Coils) <i>Function Code (0x01 & 0x02)</i>	33 (DI-1) to 44 (DI-12)	<table><tr><th>Coil Value</th><th>DI Status</th></tr><tr><td>0</td><td>No 'Low-to-High' Transition</td></tr><tr><td>1</td><td>'Low-to-High' Transition Detected</td></tr></table>	Coil Value	DI Status	0	No 'Low-to-High' Transition	1	'Low-to-High' Transition Detected						
Coil Value	DI Status													
0	No 'Low-to-High' Transition													
1	'Low-to-High' Transition Detected													

3 (b). Low-to-High Acknowledge Command

This parameter is used to acknowledge the 'Low-to-High' latched status by writing the value '1'. Reading this parameter always returns the value '0'.

Table 3.4

Run Time Parameter (Not Stored in non-volatile memory)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Holding Register <i>Function Code (0x06 & 0x10)</i>	2101	<table><tr><td>Bit 15</td><td>. . .</td><td>Bit 11</td><td>. . .</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-12 to Bit-15 DI-1 Low-to-High Acknowledge DI-2 Low-to-High Acknowledge ... DI-12 Low-to-High Acknowledge <table><tr><th>Bit Value</th><th>Result</th></tr><tr><td>0</td><td>No Effect</td></tr><tr><td>1</td><td>'Low-to-High' Status Cleared</td></tr></table>	Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0	Bit Value	Result	0	No Effect	1	'Low-to-High' Status Cleared
Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0									
Bit Value	Result													
0	No Effect													
1	'Low-to-High' Status Cleared													
Coils <i>Function Code (0x05 & 0x0F)</i>	101 (DI-1) to 112 (DI-12)	<table><tr><th>Coil Value</th><th>Result</th></tr><tr><td>0</td><td>No Effect</td></tr><tr><td>1</td><td>'Low-to-High' Status Cleared</td></tr></table>	Coil Value	Result	0	No Effect	1	'Low-to-High' Status Cleared						
Coil Value	Result													
0	No Effect													
1	'Low-to-High' Status Cleared													

4 (a). High-to-Low Latched Digital Input Status (Read-Only Parameters)

This parameter value is set to 1 upon detecting the change in status from 'Close-to-Open' for a Dry / Wet Contact Closure input or from 'High-to-Low' logic level for PNP / NPN Sensor Input. This value is latched until acknowledged by writing to 'High-to-Low Acknowledge Command' Register / Coil.

Table 3.5

Run Time Parameter (Read Only)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Input or Holding Register <i>Function Code (0x03 or 0x04)</i>	42	<table><tr><td>Bit 15</td><td>. . .</td><td>Bit 11</td><td>. . .</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-12 to Bit-15 DI-1 High-to-Low Latched Status DI-2 High-to-Low Latched Status ... DI-12 High-to-Low Latched Status <table><tr><th>Bit Value</th><th>DI Status</th></tr><tr><td>0</td><td>No 'High-to-Low' Transition</td></tr><tr><td>1</td><td>'High-to-Low' Transition Detected</td></tr></table>	Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0	Bit Value	DI Status	0	No 'High-to-Low' Transition	1	'High-to-Low' Transition Detected
Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0									
Bit Value	DI Status													
0	No 'High-to-Low' Transition													
1	'High-to-Low' Transition Detected													
Discrete Input (Coils) <i>Function Code (0x01 & 0x02)</i>	65 (DI-1) to 76 (DI-12)	<table><tr><th>Coil Value</th><th>DI Status</th></tr><tr><td>0</td><td>No 'High-to-Low' Transition</td></tr><tr><td>1</td><td>'High-to-Low' Transition Detected</td></tr></table>	Coil Value	DI Status	0	No 'High-to-Low' Transition	1	'High-to-Low' Transition Detected						
Coil Value	DI Status													
0	No 'High-to-Low' Transition													
1	'High-to-Low' Transition Detected													

4 (b). High-to-Low Acknowledge Command

This parameter is used to acknowledge the 'High-to-Low' latched status by writing the value '1'. Reading this parameter always returns the value '0'.

Table 3.6

Run Time Parameter (Not Stored in non-volatile memory)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Holding Register <i>Function Code (0x06 & 0x10)</i>	2103	<table><tr><td>Bit 15</td><td>. . .</td><td>Bit 11</td><td>. . .</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-12 to Bit-15 DI-1 High-to-Low Acknowledge DI-2 High-to-Low Acknowledge ... DI-12 High-to-Low Acknowledge <table><tr><th>Bit Value</th><th>Result</th></tr><tr><td>0</td><td>No Effect</td></tr><tr><td>1</td><td>'High-to-Low' Status Cleared</td></tr></table>	Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0	Bit Value	Result	0	No Effect	1	'High-to-Low' Status Cleared
Bit 15	. . .	Bit 11	. . .	Bit 1	Bit 0									
Bit Value	Result													
0	No Effect													
1	'High-to-Low' Status Cleared													
Discrete Input (Coils) <i>Function Code (0x05 & 0x0F)</i>	133 (DI-1) to 144 (DI-12)	<table><tr><th>Coil Value</th><th>Result</th></tr><tr><td>0</td><td>No Effect</td></tr><tr><td>1</td><td>'High-to-Low' Status Cleared</td></tr></table>	Coil Value	Result	0	No Effect	1	'High-to-Low' Status Cleared						
Coil Value	Result													
0	No Effect													
1	'High-to-Low' Status Cleared													

5. Digital Filter

This parameter helps remove any unwarranted signal noise on PNP / NPN Sensor Inputs or mechanical de-bounce on Dry / Wet Contact Closure Inputs. As illustrated in Figure 3.1 (a) & 3.1 (b) any state change (transition) is accepted only if the changed state is held constant for the time period (in milli-Second) set for the Digital Filter parameter.

Figure 3.1 (a) : Low-to-High / Open-to-Close State Change

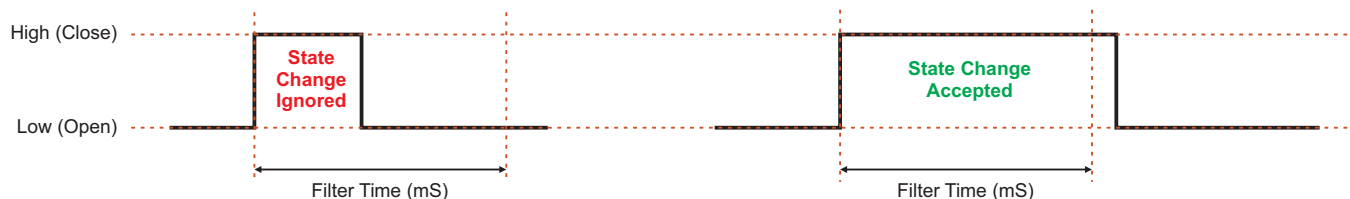


Figure 3.1 (b) : High-to-Low / Close-to-Open State Change

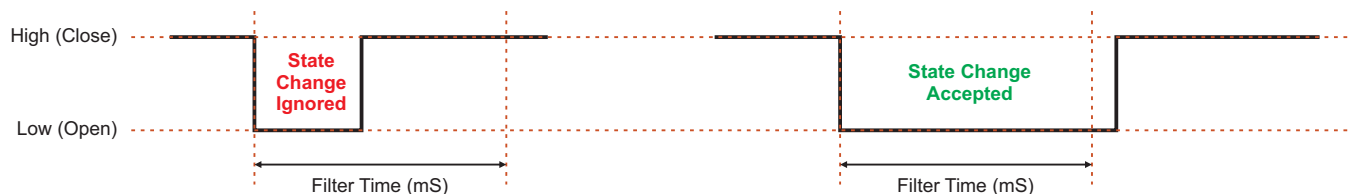


Table 3.7
Configuration Parameter (Stored in Non-Volatile memory)

Modbus Data Type	MODBUS Address	Values
Holding Registers <i>Function Code (0x06 & 0x10)</i>	2035 (DI-1) to 2046 (DI-12)	1 to 30000 mSec (Default : 10 mSec)



Section 4 DIGITAL OUTPUT PARAMETERS

1. Digital Output Function Modes & Associated Parameters

Each Digital Output can be independently programmed to function as **On-Off**, **Re-triggerable Single Pulse**, or continuous **Pulse Train** output.

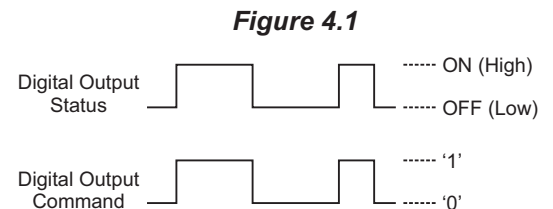
For Single Pulse output, the Pulse-Time is settable. For Pulse Train output, the Pulse-On & Pulse-Off times are settable.

The outputs are switched/triggered by writing to the Digital Output Command Register / Coils.

The three modes & the parameters are described below.

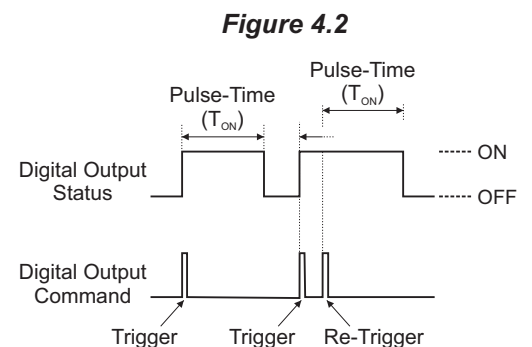
On-Off Mode (High-Low Levels)

In this mode, the output switches On (logic High) or Off (logic Low) following the Digital Output Command Value. If Digital Output Command is written '1', the output turns On. If Digital Output Command is written '0', the output turns OFF. Refer to Figure 4.1.



Re-triggerable Single Pulse Mode

In this mode, the output generates a single Logic High Pulse whenever the Digital Output Command is written '1'. The module automatically writes '0' to the Digital Output Command as soon as the output pulse is initiated. If the Output Command is again written '1' while the pulse is still Logic High, the pulse time restarts (Re-triggered). Refer to Figure 4.2.



Pulse Train Mode

In this mode, the output initiates a continuous series of High-Low Pulses when the Digital Output Command is written '1'. The Pulse Train continues as long as the Digital Output Command remains '1'. The Pulse-Train stops immediately upon writing '0' to the Digital Output Command. Refer to Figure 4.3.

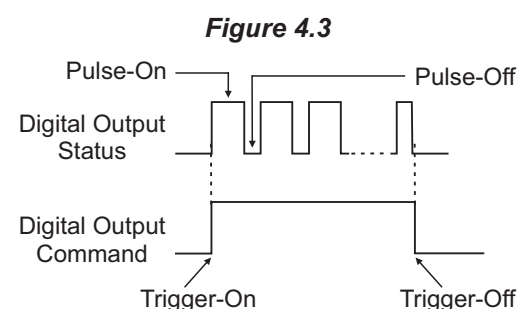


Table 4.1 (a) : Output Status Command Register

Run-Time Parameter

Modbus Data Type	MODBUS Address	Values																	
Bit-Mapped Holding Register Function Code (0x06 & 0x10)	3001	Bit 15 ... Bit 3 Bit 2 Bit 1 Bit 0 Ignore Bit-4 to Bit-15 DO-1 Command DO-2 Command DO-3 Command DO-4 Command Write Operation (Bit Positions 0 to 3) <table><thead><tr><th>Bit Value</th><th>Mode</th><th>DO Status</th></tr></thead><tbody><tr><td rowspan="3">1</td><td>On-Off</td><td>Output ON</td></tr><tr><td>Single Pulse</td><td>Start a new pulse or re-trigger a running pulse</td></tr><tr><td>Pulse Train</td><td>Start / Keep running a Pulse-Train</td></tr><tr><td rowspan="3">0</td><td>On-Off</td><td>Output OFF</td></tr><tr><td>Single Pulse</td><td>No effect</td></tr><tr><td>Pulse Train</td><td>Stop Pulse-Train</td></tr></tbody></table>	Bit Value	Mode	DO Status	1	On-Off	Output ON	Single Pulse	Start a new pulse or re-trigger a running pulse	Pulse Train	Start / Keep running a Pulse-Train	0	On-Off	Output OFF	Single Pulse	No effect	Pulse Train	Stop Pulse-Train
Bit Value	Mode	DO Status																	
1	On-Off	Output ON																	
	Single Pulse	Start a new pulse or re-trigger a running pulse																	
	Pulse Train	Start / Keep running a Pulse-Train																	
0	On-Off	Output OFF																	
	Single Pulse	No effect																	
	Pulse Train	Stop Pulse-Train																	
Coils Function Code (0x05 & 0x0F)	301 (DO-1) to 304 (DO-4)	Write Operation (Coil Address 301 to 304) <table><thead><tr><th>Coil Value</th><th>Mode</th><th>DO Status</th></tr></thead><tbody><tr><td rowspan="3">1</td><td>On-Off</td><td>Output ON</td></tr><tr><td>Single Pulse</td><td>Start a new pulse or re-trigger a running pulse</td></tr><tr><td>Pulse Train</td><td>Start / Keep running a Pulse-Train</td></tr><tr><td rowspan="3">0</td><td>On-Off</td><td>Output OFF</td></tr><tr><td>Single Pulse</td><td>No effect</td></tr><tr><td>Pulse Train</td><td>Stop Pulse-Train</td></tr></tbody></table>	Coil Value	Mode	DO Status	1	On-Off	Output ON	Single Pulse	Start a new pulse or re-trigger a running pulse	Pulse Train	Start / Keep running a Pulse-Train	0	On-Off	Output OFF	Single Pulse	No effect	Pulse Train	Stop Pulse-Train
Coil Value	Mode	DO Status																	
1	On-Off	Output ON																	
	Single Pulse	Start a new pulse or re-trigger a running pulse																	
	Pulse Train	Start / Keep running a Pulse-Train																	
0	On-Off	Output OFF																	
	Single Pulse	No effect																	
	Pulse Train	Stop Pulse-Train																	

Table 4.1 (b) : Output Function Mode

Configuration Parameter (Stored in Non-Volatile memory)

Modbus Data Type	MODBUS Address	Values								
Holding Register <i>Function Code (0x06 & 0x10)</i>	3008 (DO-1) to 3011 (DO-4)	<table><tr><th>Value</th><th>Function Mode</th></tr><tr><td>0</td><td>ON-OFF</td></tr><tr><td>1</td><td>Single Pulse</td></tr><tr><td>2</td><td>Pulse Train</td></tr></table> (Default : ON-OFF Mode)	Value	Function Mode	0	ON-OFF	1	Single Pulse	2	Pulse Train
Value	Function Mode									
0	ON-OFF									
1	Single Pulse									
2	Pulse Train									

Table 4.1 (c) : Pulse-ON Time

Run-Time / Configuration Parameter (Refer Parameter : 'Save Pulse-ON & Pulse-OFF Times to Non-Volatile Memory')

Modbus Data Type	MODBUS Address	Values
Holding Register <i>Function Code (0x06 & 0x10)</i>	3040 (DO-1) to 3043 (DO-4)	Applicable for 'Single Pulse' & 'Pulse-Train' Mode Only 0 to 30000 Counts (0.01 to 300 Seconds) 1 count = 10 milli-Seconds (Default : 10 Counts)

Table 4.1 (d) : Pulse-OFF Time

Run-Time / Configuration Parameter (Refer Parameter : 'Save Pulse-ON & Pulse-OFF Times to Non-Volatile Memory')

Modbus Data Type	MODBUS Address	Values
Holding Register <i>Function Code (0x06 & 0x10)</i>	3072 (DO-1) to 3075 (DO-4)	Applicable for 'Pulse-Train' Mode Only 0 to 30000 Counts (0.01 to 300 Seconds) 1 count = 10 milli-Seconds (Default : 10 Counts)

Table 4.1 (e) : Save Pulse-ON & Pulse-OFF Times to Non-Volatile Memory

Modbus Data Type	MODBUS Address	Values						
Holding Register <i>Function Code (0x06 & 0x10)</i>	3104	Applicable for ‘Single Pulse’ & ‘Pulse-Train’ Mode Only <table><tr><th>Value</th><th>Save to Memory</th></tr><tr><td>0</td><td>No</td></tr><tr><td>1</td><td>Yes</td></tr></table> If Pulse ON and / or Pulse OFF times are constant for a given application, it is advisable to store these values in module’s non-volatile memory. This feature eliminates the need for programming the Pulse ON & Pulse OFF parameter values each time the module is powered. To store values in non-volatile memory, set this Register value (Modbus Address 3104) to ‘1’ after setting the values for Pulse ON & Pulse OFF parameters.	Value	Save to Memory	0	No	1	Yes
Value	Save to Memory							
0	No							
1	Yes							

2. Output Fail-Safe Status

Each of the 12 outputs can be independently enabled to enter into a fail-safe On or Off output state. If enabled, the outputs enter into the fail-safe states if there is no communication (read/write request) from the host to the module for a user-programmed time interval.

The following three sets of Registers / Coils configure the Fail-Safe feature.

Table 4.2 (a) : 'Fail-Safe Enable' Register / Coils
Configuration Parameter (Stored in Non-Volatile memory)

Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Holding Register <i>Function Code (0x06 & 0x10)</i>	3003	<table><tr><td>Bit 15</td><td>. . . .</td><td>Bit 3</td><td>Bit 2</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-4 to Bit-15 DO-1 Fail-Safe Enable / Disable DO-2 Fail-Safe Enable / Disable DO-3 Fail-Safe Enable / Disable DO-4 Fail-Safe Enable / Disable <table><tr><th>Bit Value</th><th>Enable / Disable</th></tr><tr><td>0</td><td>Fail-Safe Disable</td></tr><tr><td>1</td><td>Fail-Safe Enable</td></tr></table> (Default : Disable)	Bit 15		Bit 3	Bit 2	Bit 1	Bit 0	Bit Value	Enable / Disable	0	Fail-Safe Disable	1	Fail-Safe Enable
Bit 15		Bit 3	Bit 2	Bit 1	Bit 0									
Bit Value	Enable / Disable													
0	Fail-Safe Disable													
1	Fail-Safe Enable													
Coils <i>Function Code (0x05 & 0x0F)</i>	333 (DO-1) to 336 (DO-4)	<table><tr><th>Coil Value</th><th>Enable / Disable</th></tr><tr><td>0</td><td>Fail-Safe Disable</td></tr><tr><td>1</td><td>Fail-Safe Enable</td></tr></table> (Default : Disable)	Coil Value	Enable / Disable	0	Fail-Safe Disable	1	Fail-Safe Enable						
Coil Value	Enable / Disable													
0	Fail-Safe Disable													
1	Fail-Safe Enable													

Table 4.2 (b) : 'Fail-Safe Status' Register / Coils
 (This parameter is applicable only if 'Fail-Safe' is enabled)
 Configuration Parameter (Stored in Non-Volatile memory)

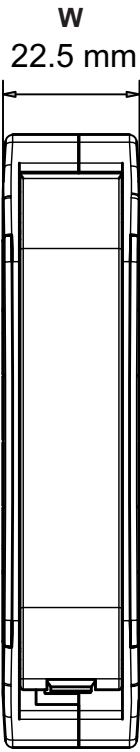
Modbus Data Type	MODBUS Address	Values												
Bit-Mapped Holding Register Function Code (0x06 & 0x10)	3005	<table><tr><td>Bit 15</td><td>. . . .</td><td>Bit 3</td><td>Bit 2</td><td>Bit 1</td><td>Bit 0</td></tr></table> Ignore Bit-4 to Bit-15 DO-1 Fail-Safe Output Status DO-2 Fail-Safe Output Status DO-3 Fail-Safe Output Status DO-4 Fail-Safe Output Status <table><tr><th>Bit Value</th><th>Output Status</th></tr><tr><td>0</td><td>OFF</td></tr><tr><td>1</td><td>ON</td></tr></table> (Default : OFF)	Bit 15		Bit 3	Bit 2	Bit 1	Bit 0	Bit Value	Output Status	0	OFF	1	ON
Bit 15		Bit 3	Bit 2	Bit 1	Bit 0									
Bit Value	Output Status													
0	OFF													
1	ON													
Coils Function Code (0x05 & 0x0F)	365 (DO-1) to 368 (DO-4)	<table><tr><th>Coil Value</th><th>Output Status</th></tr><tr><td>0</td><td>OFF</td></tr><tr><td>1</td><td>ON</td></tr></table> (Default : OFF)	Coil Value	Output Status	0	OFF	1	ON						
Coil Value	Output Status													
0	OFF													
1	ON													

Table 4.2 (c) : 'Fail-Safe Time Period' Register
 (This parameter is applicable only if 'Fail-Safe' is enabled)
 Configuration Parameter (Stored in Non-Volatile memory)

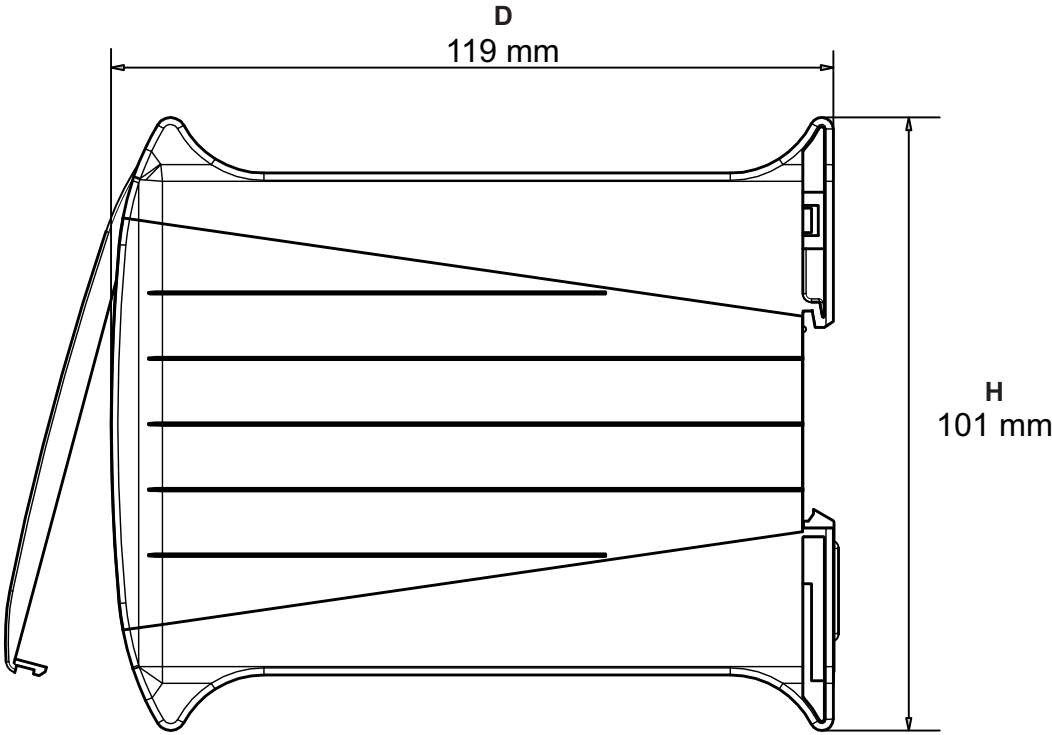
Modbus Data Type	MODBUS Address	Values
Holding Register <i>Function Code (0x06 & 0x10)</i>	3007	1 to 300 Seconds (Default : 10 Seconds)



Section 5
MECHANICAL DIMENSIONS



Front View



Side View

Width (W)	22.5 mm
Height (H)	101.0 mm
Depth (D)	119.0 mm



Section 6

CONFIGURING COMMUNICATION PARAMETERS

The Module supports industry standard **MODBUS RTU over Serial** Protocol for Configuration and Operation.

The Serial Communication Port specification are shown in Table 6.1 below.

Table 6.1

Port	RS485, 2-wire, Half duplex, Start-stop synchronized	
Protocol	Modbus RTU	
Communication Parameters	Parameter	Settings
	Slave ID	1 to 127
	Baud Rate	2400, 4800, 9600, 19200, 38400 bps
	Parity	None (1 or 2 Stop Bits) Even (1 Stop Bit) odd (1 Stop Bit)
Max. No. of Units per Loop	31	
Maximum Distance	1200 Meters	

The Module is shipped from the factory with the following default values for the Communication Parameters.

Slave ID : 1	Baud Rate : 9600 bps	Parity : Even
--------------	----------------------	---------------

The above parameters can be altered to match with the Host (Master) parameters by putting the Module in **Configuration Mode**. In Configuration Mode, the Module always communicates with the host with the **fixed** communication parameter values (Slave ID : **1**, Baud Rate : **9600** & Parity : **None**) regardless of the actual set values. The user set values are applicable only when the Module is put back in the **Normal Operation Mode**.

A Slide Switch Set is provided on the Module, as shown in the Figure 6.1, to select between the Configuration and Normal Operation modes. The Table 6.2 shows the Switch Positions and the respective mode.

It is important to note that the switch position is detected only upon power-up. Select the desired Mode while the Module is OFF. That is changing the switch position while the Module is powered does not have any effect on the Mode.

Figure 6.1

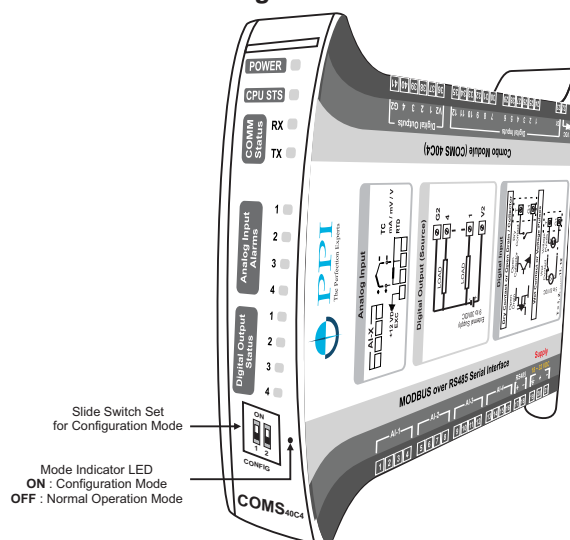
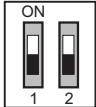
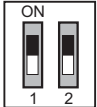


Table 6.2

Switch Position	 Down	 Up
Mode Indicator	OFF	ON
Operation Mode	Normal	Configuration
Communication Parameter Values	User Set values for Module Slave ID, Baud Rate & Parity	Module Slave ID : 1 Baud Rate : 9600 Parity : None

The Communication Parameters values can be altered by using the MODBUS RTU protocol while the Module is in Configuration Mode. Set the host (Master) Baud Rate to “9600 bps” and Parity to “None”. The MODBUS Addresses and Settings for the Module communication parameters are listed in the Table 6.3 below.

Table 6.3

Parameter Description	MODBUS Address	Settings (Default Value)												
Module Slave ID Unique numeric value assigned to the indicator for identification by the host. Set the value as required by the host.	1	1 to 127 (Default : 1)												
Baud Rate Communication speed in ‘Bits per Second’. Set the value to match with the host baud rate.	2	<table><tr><th>Value</th><th>Baud Rate</th></tr><tr><td>0</td><td>2400 bps</td></tr><tr><td>1</td><td>4800 bps</td></tr><tr><td>2</td><td>9600 bps</td></tr><tr><td>3</td><td>19200 bps</td></tr><tr><td>4</td><td>38400 bps</td></tr></table> (Default : 9600 bps)	Value	Baud Rate	0	2400 bps	1	4800 bps	2	9600 bps	3	19200 bps	4	38400 bps
Value	Baud Rate													
0	2400 bps													
1	4800 bps													
2	9600 bps													
3	19200 bps													
4	38400 bps													
Parity One of the communication error trapping features. Set the data packet parity as implemented by the host protocol.	3	<table><tr><th>Value</th><th>Parity</th></tr><tr><td>0</td><td>None</td></tr><tr><td>1</td><td>Even</td></tr><tr><td>2</td><td>Odd</td></tr></table> (Default : Even)	Value	Parity	0	None	1	Even	2	Odd				
Value	Parity													
0	None													
1	Even													
2	Odd													



Section 7 PC BASED DEVICE SETUP UTILITY

OVERVIEW

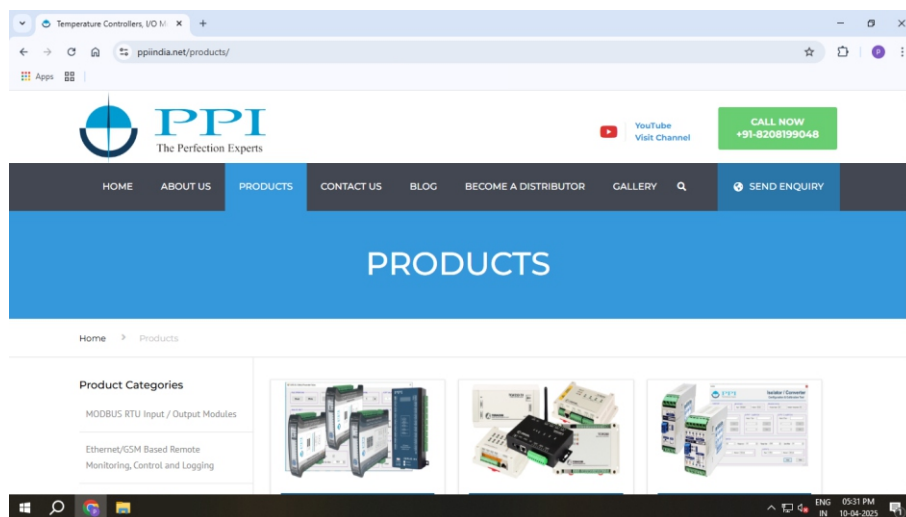
UniSet is a free Windows-based configuration utility developed by PPI to simplify the setup, parameter configuration, and monitoring of its MODBUS-compatible product range. It eliminates the need for manual MODBUS commands and streamlines device commissioning and testing.

This utility offers a quick, reliable, and user-friendly interface for configuring and validating this device during initial setup and field deployment.

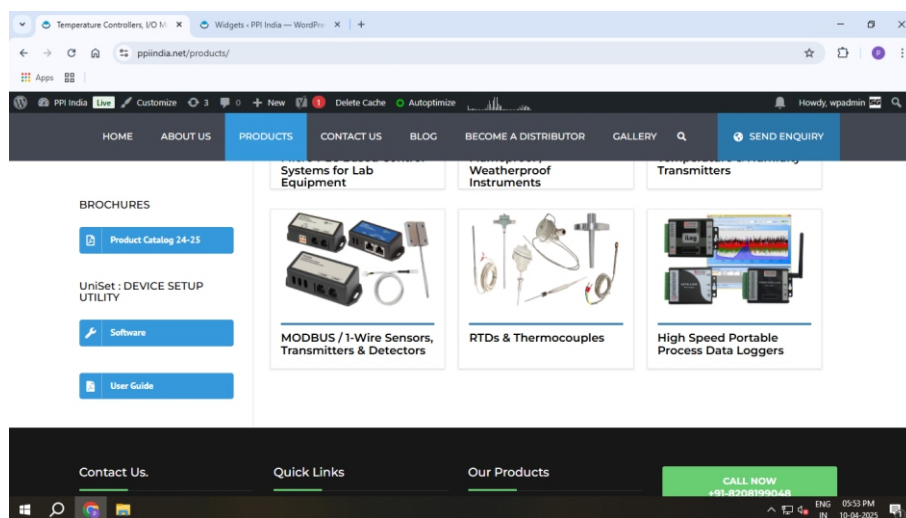
7.1 DOWNLOADING THE SETUP TOOL

The tool is available for **free download** from the **PPI website** and can be accessed from the **PRODUCTS** section. To download and launch the tool:

1. **Visit** www.ppiindia.net and click on the **PRODUCTS** tab in the main navigation menu.



2. In the **left-hand panel**, scroll to **UniSet : Device Setup Utility**.



3. Two buttons will be visible under this section:

- **Software** – Click to download the configuration utility archive (IO-Module-Configuration-Tool.rar).
- **User Guide** – Click to download the PDF manual for reference.

4. After downloading the archive file:

- Extract the contents into a folder (e.g., IO-Module-Configuration-Tool).
- Open the folder and double-click on IO Module Configuration Tool.exe to launch the application.

The **UniSet** interface for this device includes the following key task panels:

7.2 DEVICE COM PORT SETTING

Used to select the appropriate COM port and configure baud rate, parity, and slave ID to match the connected device.

Device Com Port Configuration

PC COM PORT

Select Port Name: COM1

DEVICE COM PORT

Slave ID: 1

Parity: Even

Baud Rate: 9600 bps

Read Write

7.3 PARAMETER SETTINGS

Used to configure parameters for Analog Input channels, Digital Input channels, and Digital Output channels.

The user can save (Write) or retrieve (Read) the parameter configuration to the Device or to a File.

COMS-40C4: Default Parameter Values

FILE OPERATION Read Write

DEVICE OPERATION Read Write

Analog Inputs Digital Inputs Digital Outputs

Select Channel: 1

AI - 1

Type: 4 - 20 mA Zero Offset: 0 Resolution: 1

Units: °C

DC SIGNAL Low: 4.00 High: 20.00

DC RANGE Low: 0 High: 1000

CLIPPING Low Clip: [checked] High Clip: [checked]

Low Clip Value: 0 High Clip Value: 1000

ALARM - 1 Type: Low Set Point: -15000 Hysteresis: 2 Inhibit: [checked]

ALARM - 2 Type: Low Set Point: -30000 Hysteresis: 2 Inhibit: [unchecked]

ALARM - 3 Type: High Set Point: 15000 Hysteresis: 2 Inhibit: [unchecked]

ALARM - 4 Type: High Set Point: 30000 Hysteresis: 2 Inhibit: [checked]

Digital Inputs **Digital Outputs**

DI-Type: Input Type: Wet Contact

DI-1 Filter Time (mSec): 1000 DI-2 Filter Time (mSec): 10 DI-3 Filter Time (mSec): 1000 DI-4 Filter Time (mSec): 1000

DI-5 Filter Time (mSec): 200 DI-6 Filter Time (mSec): 90 DI-7 Filter Time (mSec): 90 DI-8 Filter Time (mSec): 200

DI-9 Filter Time (mSec): 300 DI-10 Filter Time (mSec): 100 DI-11 Filter Time (mSec): 500 DI-12 Filter Time (mSec): 1000

7.4 ON-LINE MONITORING

Displays real-time process values, alarms, and I/O statuses (as applicable). Useful for system diagnostics and validation.

Process Status

COMS40C4

15-07-2024 15:16:47

Analog Inputs

Digital Inputs

Digital Outputs

Channel Name	PV	ALARM-1	ALARM-2	ALARM-3	ALARM-4
Chan-1	-1.4				
Chan-2	-1.5				
Chan-3	60.4				
Chan-4	44.1				

Process Status

COMS40C4

15-07-2024 15:23:49

Analog Inputs

Digital Inputs

Digital Outputs

DO - 1

☒ ON ☐ OFF

DO - 2

☒ ON ☐ OFF

DO - 3

☒ ON ☐ OFF

DO - 4

☐ ON ☒ OFF

Raed

Write

APPENDIX A DC LINEAR SIGNAL INTERFACE

This appendix describes the parameters required to interface process transmitters that produce Linear DC Voltage (mV/V) or Current (mA) signals in proportion to the measured process values. A few examples of such transmitters are;

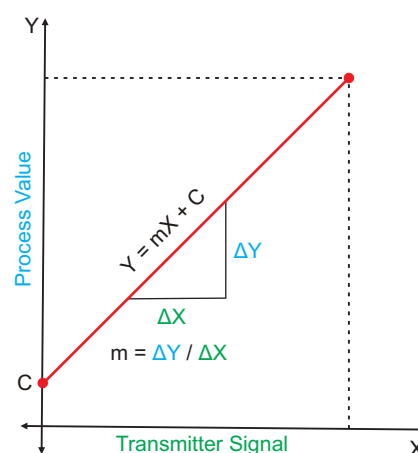
1. Pressure Transmitter producing **4 to 20 mA** for **0 to 5 psi**
2. Relative Humidity Transmitter producing **1 to 4.5 V** for **5 to 95 %RH**
3. Temperature Transmitter producing **0 to 20 mA** for **-50 to 250 °C**

The instrument (indicator / controller / recorder) that accepts the linear signal from the transmitter computes the measured process value by solving the mathematical equation for Straight-Line in the form:

$$Y = mX + C$$

Where;

- X : Signal Value from Transmitter
- Y : Process Value Corresponding to Signal Value X
- C : Process Value Corresponding to X = 0 (Y-intercept)
- m : Change in Process Value per unit Change in Signal Value (Slope)



As is evident from the aforementioned transmitter examples, different transmitters produce signals varying both in type (mV/V/mA) and range. Most PPI instruments, thus, provide programmable Signal Type and Range to facilitate interface with a variety of transmitters. A few industry standard signal types and ranges offered by the PPI instruments are: $\pm 80\text{mV}$, $\pm 5\text{V}$, ± 1 to $\pm 5\text{V}$, $\pm 10\text{V}$, 0-20 mA, 4-20 mA, etc.

Also, the output signal range (e.g. 1 to 4.5 V) from different transmitters corresponds to different process value range (e.g. 5 to 95 %RH); the instruments thus also provide facility for programming the measured process value range with programmable Resolution.

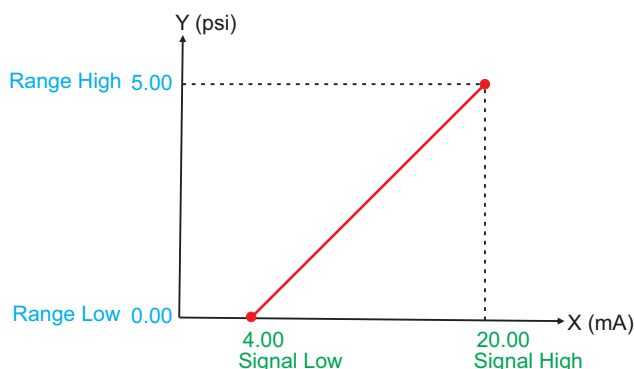
The linear transmitters usually specify two signal values (Signal Low and Signal High) and the corresponding Process Values (Range Low and Range High). In the example Pressure Transmitter above; the Signal Low, Signal High, Range Low & Range High values specified are: 4 mA, 20 mA, 0 psi & 5 psi, respectively.

In summary, the following 6 parameters are required for interfacing Linear Transmitters:

1. Input Type : Standard DC Signal Type in which the transmitter signal range fits (e.g. 4-20 mA)
2. Signal Low : Signal value corresponding to Range Low process value (e.g. 4.00 mA)
3. Signal High : Signal value corresponding to Range High process value (e.g. 20.00 mA)
4. PV Resolution : Resolution (least count) with which to compute process value (e.g. 0.01)
5. Range Low : Process value corresponding to Signal Low value (e.g. 0.00 psi)
6. Range High : Process value corresponding to Signal High value (e.g. 5.00 psi)

The following examples illustrate appropriate parameter value selections.

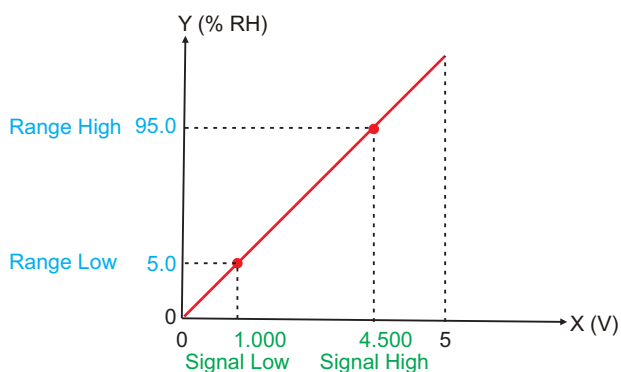
Example 1: Pressure Transmitter producing **4 to 20 mA** for **0 to 5 psi**



Presume the pressure is to be measured with 0.01 Resolution, that is 0.00 to 5.00 psi.

Input Type	: 4-20 mA
Signal Low	: 4.00 mA
Signal High	: 20.00 mA
PV Resolution	: 0.01
Range Low	: 0.00
Range High	: 5.00

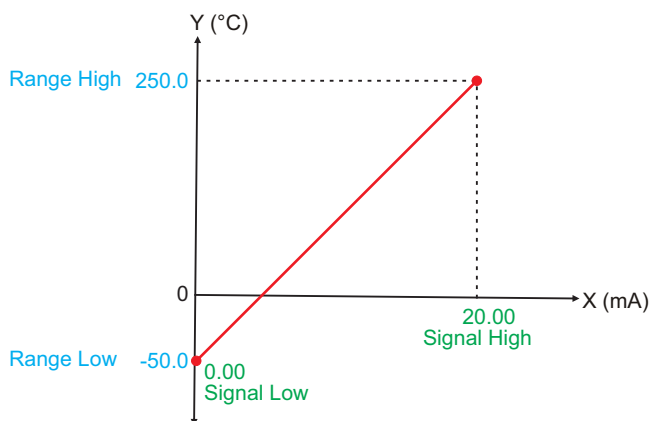
Example 2: Relative Humidity Transmitter producing **1 to 4.5 V** for **5 to 95 %RH**



Presume the humidity is to be measured with 0.1 Resolution, that is 0.0 to 100.0 %.

Input Type	: 0-5 V
Signal Low	: 1.000 V
Signal High	: 4.500 V
PV Resolution	: 0.1
Range Low	: 5.0
Range High	: 95.0

Example 3: Temperature Transmitter producing **0 to 20 mA** for **-50 to 250 °C**



Presume the Temperature is to be measured with 0.1 Resolution, that is -50.0 to 250.0°C.

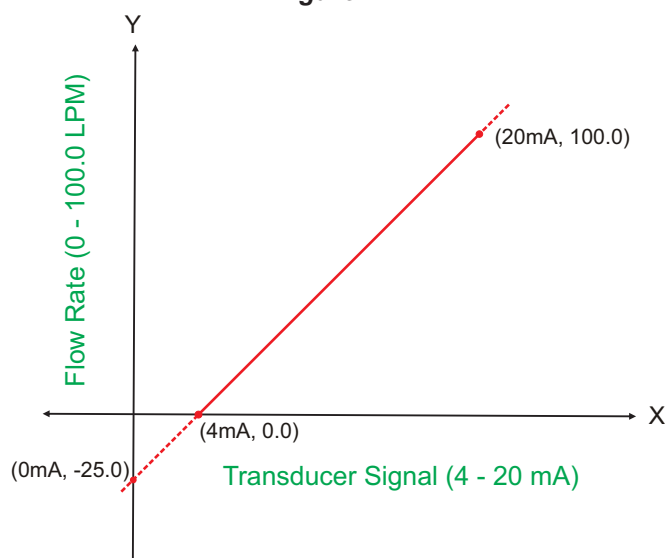
Input Type	: 0-20 mA
Signal Low	: 0.00 mA
Signal High	: 20.00 mA
PV Resolution	: 0.1
Range Low	: -50.0
Range High	: 250.0

APPENDIX B BOTTOM / TOP CLIPPING

For mA/mV/V inputs the measured PV is a scaled value between the set values for 'PV Range Low' and 'PV Range High' parameters corresponding to the Signal Minimum and Signal Maximum values respectively. Refer Appendix A.

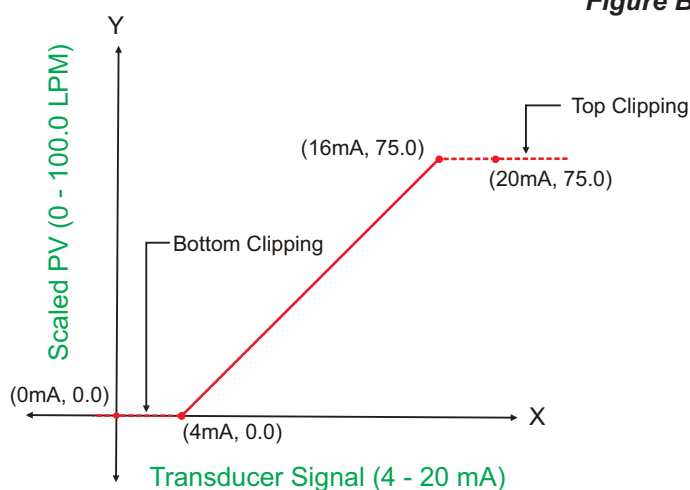
The Figure B.1 below illustrates an example of flow rate measurement using a transmitter / transducer producing a signal range of 4 - 20 mA corresponding to 0.0 to 100.0 Liters per Minute (LPM).

Figure B.1



If this transmitter is to be used for a system having a flow rate range of 0.0 to 75.0 LPM then the actual useful signal range from the example transmitter is 4 mA (~ 0.0 LPM) to 16 mA (~ 75.0 LPM) only. If no Clipping is applied on the measured flow rate then the scaled PV will also include 'out-of-range' values for the signal values below 4 mA and above 16 mA (may be due to open sensor condition or calibration errors). These out-of-range values can be suppressed by enabling the Bottom and/or Top Clippings with appropriate Clip values as shown in figure B.2 below.

Figure B.2



Parameter Values

PV Range Low	: 0.0
PV Range High	: 100.0
Enable Bottom Clipping	: Yes
Bottom Clip Value	: 0.0
Enable Top Clipping	: Yes
Top Clip Value	: 75.0

APPENDIX C

PROCESS VALUE IN 'FLOAT' DATA FORMAT

The measured Process Values for all channels can be read in 32-Bit Single Precision Float format at Modbus Addresses listed in the following table.

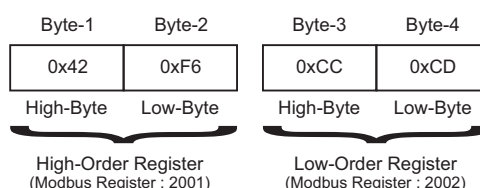
Read-Only Parameter

Parameter Description	MODBUS Address	Values								
Process Value Measured Temperature (in °C / °F) for Thermocouple / RTD inputs or Scaled Counts for DC Volts / mA inputs.	2001 (AI-1) to 2008 (AI-4)	Single Precision Float values from -30000 to +30000 representing the measured process values. Refer Table 2.3 (Section 2) for the various input types and the corresponding measured ranges. The following constant counts indicate PV Errors. <table><tr><th>Value</th><th>PV Error Type</th></tr><tr><td>-32768</td><td>Under Range</td></tr><tr><td>+32752</td><td>Over Range</td></tr><tr><td>+32767</td><td>Sensor Open</td></tr></table>	Value	PV Error Type	-32768	Under Range	+32752	Over Range	+32767	Sensor Open
Value	PV Error Type									
-32768	Under Range									
+32752	Over Range									
+32767	Sensor Open									

The Process Values can be read in IEEE single precision floating point format in two adjacent 16-bit Modbus registers, the high order register first. The high-order register always starts at an odd Modbus address. For example, the process value for channel-1 is read in addresses 2001 (high-order register) & 2002 (low-order register). Within the register, the high-order byte is sent first in accordance to standard Modbus RTU format. The following example illustrates the register & byte sequence.

	Decimal Format	Hexa-decimal Format
Process Value for Channel-1	123.4	0x42F6CCCD

The data is transferred in the following Byte-Sequence.



The Process Values for Thermocouple & RTD Pt100 Inputs is always transferred with 0.1 count resolution.

The resolution for Process Values for DC Linear inputs is dependent on the value set for the Parameter *DC Resolution* (Modbus Addresses : 115 to 118). For example, if the dc resolution parameter value is 2 & if the measured scaled integer counts are 12345 then the communicated process value is 123.45.



APPENDIX D ALARM STATUS AS DISCRETE INPUTS / COILS

Alarm Status (Read Only)

Modbus Data Type	MODBUS Address	Values						
Alarm-1 Status <i>Function Code (0x01 & 0x02)</i>	417 (AI-1) to 420 (AI-4)	<table><tr><th>Coil Value</th><th>Status</th></tr><tr><td>0</td><td>Alarm OFF</td></tr><tr><td>1</td><td>Alarm ON</td></tr></table>	Coil Value	Status	0	Alarm OFF	1	Alarm ON
Coil Value	Status							
0	Alarm OFF							
1	Alarm ON							
Alarm-2 Status <i>Function Code (0x01 & 0x02)</i>	433 (AI-1) to 436 (AI-4)							
Alarm-3 Status <i>Function Code (0x01 & 0x02)</i>	449 (AI-1) to 452 (AI-4)							
Alarm-4 Status <i>Function Code (0x01 & 0x02)</i>	465 (AI-1) to 468 (AI-4)							



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