



control solutions

TERACOM



TCW210-TH Temperature and humidity data logger

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USER MANUAL

www.teracomsystems.com

TCW210-TH is a temperature and humidity data logger with an embedded WEB server. Real-time data and charts of temperature, humidity and dew point can be monitored with a standard web browser (no special software is needed). Standard protocols as SNMP, MODBUS/TCP, and HTTP/API are available for M2M applications. The device supports also interface to popular IoT analytics – ThinkSpeak.

The Ethernet temperature logger supports up to eight temperature or humidity-temperature sensors. All they can be connected either to the 1-Wire interface, popular for home automation or to more robust MODBUS RTU over RS-485.

All monitored parameters can be recorded, in internal FLASH memory. The records are made on the previous set time interval and/or on an alarm condition. The memory is large enough for at least 36 days with records on every minute. The log file can be periodically uploaded on a dedicated server by HTTP/HTTPS Post. The stored data can be monitored on 4 graph pages.

XML/JSON file with all monitored parameters can periodically upload to a dedicated server by HTTP/HTTPS Post.

For every monitored parameter e-mails and SNMP traps for up to 5 recipients can be sent. Alarm alert can also be sent by HTTP/HTTPS Post with XML/JSON status files.

2. Features

- Data logger for up to 70000 records;
- 1-Wire and MODBUS RTU sensors support;
- HTTP API commands;
- Periodical HTTP/HTTPS Post of XML/JSON status files for client-server systems;
- SNMP v.2 support;
- SNMP traps to up to 5 recipients like alarm alert;
- MODBUS TCP/IP support;
- SMTP with TLS encryption;
- TLS 1.0, TLS 1.1 and TLS 1.2 support;
- e-mails to up to 5 recipients like alarm alert;
- ThinkSpeak service support;
- NTP support;
- Back-up/Restore of configurations;
- Dynamic DNS support;
- 10/100 Mb Ethernet connectivity;
- Auto-MDIX;
- Port changing for HTTP, SNMP and MODBUS TCP/IP;
- Password protected WEB based configuration and control;
- Extended working temperature range;
- Wide power supply voltage range;
- Remote firmware update.

3. Applications

TCW210-TH is suitable for environmental monitoring, building, and industrial automation.

It works very well for monitoring temperature and humidity as a standalone device using a WEB browser only or as a part of small to large industrial control systems for SCADA (supervisory control and data acquisition).

A few application examples - pharmaceutical and food processing and storage, clean rooms, laboratories, HVAC systems, greenhouses and farms, electronic assembly etc.

4. Specifications

- Physical characteristics
Dimensions: 130 x 70 x 30 mm
Weight: 140 g
- Environmental limits
Operating temperature range: -20 to 55°C
Storage temperature range: -25 to 60°C
Operating relative humidity range: 5 to 85% (non-condensing)
- Warranty
Warranty period: 3 years
- Power requirements
Input Voltage: 10 to 32 VDC
Input Current: 170 mA @ 12 VDC
- 1-Wire and RS485 interface
Output voltage (+VW): 5.0 ± 0.3 VDC
Maximum output current (+VW): 0.2 A
- Internal FLASH memory
Endurance: 100 000 cycles (Every settings change is a memory cycle.)

5. LED indicators

The following indicators show the status of the controller:

- **PWR** (red) – in working mode shines, flashes together with STS if there is a hardware error;
- **STS** (yellow) – flashes when the main program of the controller is executed;
- **NET** (orange) – indicates the network connection status - ON when a link is established, flashing when there is an activity.

6. Installation and setup

This device must be installed by qualified personnel.

This device must not be installed directly outdoors.

The installation consists of mounting the device, connecting to an IP network, connecting inputs and outputs, providing power and configuring via a web browser.

6.1. Mounting

TCW210-TH should be mounted in a clean and dry location on a not flammable surface. Ventilation is recommended for installations where the ambient air temperature is expected to be high.

Maintain spacing between adjacent equipment. Allow 50 mm of space on all sides, as shown in Appendix A, this provides ventilation and electrical isolation.

6.2. Connection

Attention! Disconnect power supply before wiring.

The correct wiring procedure is as follows:

- Make sure power is turned off;
- Apply all sensors;
- Apply power.

Make sure that cables are properly attached. Not proper wiring and configuration can cause permanent damage to TCW210-TH or the equipment to which it is connected or both.



Connector 1	Ethernet - RJ45	Connector 4	Pin1 – not connected (most left) Pin2 – not connected
Connector 2	Power - 2.1x5.5mm connector, central positive		Pin3 – not connected Pin4 – Line B- Pin5 – Line A+ Pin6 – not connected Pin7 – +VDD Pin8 – GND
Connector 3	Pin1 – GND (most left) Pin2 – GND Pin3 – 1-Wire Data Pin4 – 1-Wire GND Pin5 – +VDD Pin6 – +VDD (most right)		

6.2.1. Power supply

TCW210-TH is designed to be supplied by adapter SYS1421-0612-W2E or similar, intended for use in the conditions of overvoltage category II, and prior assessed for compliance with safety

requirements. The power supply equipment shall be resistant to short circuit and overload in a secondary circuit.

When in use, do not position the equipment so that it is difficult to disconnect the device from the power supply.

6.2.2. 1-Wire interface

1-Wire is a registered trademark of Maxim Integrated Products, Inc. It is designed to connect several sensors over short wiring. It is not suitable for long distances or environments with EMC interference.

The maximum number of sensors (1-Wire or RS-485) connected to TCW210-TH is 8.

The device supports temperature and humidity-temperature sensors. Connected sensors are automatically detected and the appropriate dimension is assigned.

It is strongly recommended to use “daisy-chained” (linear topology) for multi-sensors systems:



It is strongly recommended to use only UTP/FTP cables and keep total cable length up to 30m. Although functionality has been achieved in the longer distance, we cannot guarantee error-free operation over mentioned wiring length. We recommend reading Maxim’s 1-Wire tips at <http://www.maxim-ic.com/app-notes/index.mvp/id/148>.

We guarantee proper operation only with Teracom 1-Wire sensors.

6.2.3. RS-485 interface

RS-485 is a standard for serial communications systems defined by Telecommunications Industry Association (TIA) and Electronic Industries Alliance (EIA). Implementing the standard, communication systems can be used effectively over long distances and in electrically noisy (industrial) environments.

The maximum number of sensors (1-Wire or RS-485) connected to TCW210-TH is 8.

The device supports temperature and humidity-temperature sensors.

MODBUS RTU protocol specifies that address of the device should be between 1 and 247. The user should take care of appropriate address settings.

For multi-sensors systems “daisy-chained” (linear topology) should be used:



Interconnections are realized by UTP/FTP cables with RJ-45 connectors. The popular Ethernet wiring standard ANSI/TIA/EIA T568B is used:

Pin#	RJ45
1	Orange/White
2	Orange
3	Green/White
4	Blue
5	Blue/White
6	Green
7	Brown/White
8	Brown

It is recommended to use standard patch cables for LAN networks.

Special attention should be paid on termination of the bus in the last sensor.

We recommend keeping total cable length up to 30 m, although the RS-485 interface works over a much longer distance.

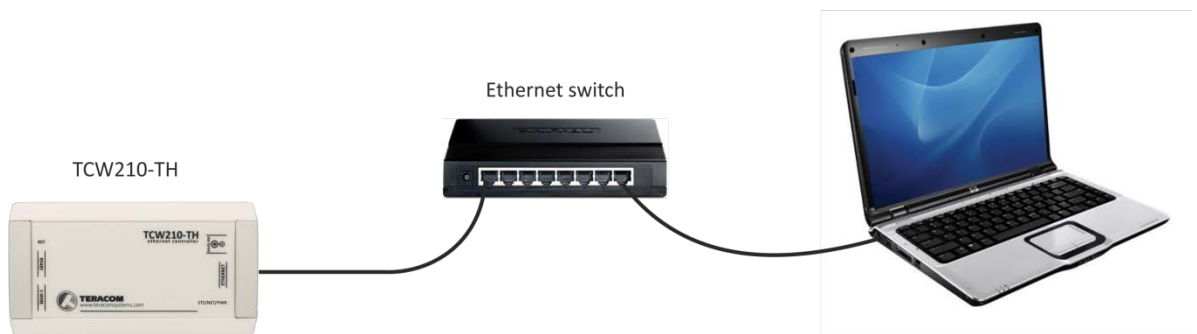
Attention!

Special attention should be paid on termination of the bus.

The last sensor in the chain should have a terminator installed on the free RJ-45 socket.

6.2.4. Network connection

The Ethernet port of TCW210-TH should be connected to 10/100 Base-T Ethernet hub, switch or router.



For setup, TCW210-TH may be connected directly to the Ethernet port on a computer. The device support Auto-MDIX and it is not necessary to use “crossover” cable, standard “straight-through” can be also used.



TCW210-TH can be used in a wireless network by connecting through a wireless router.

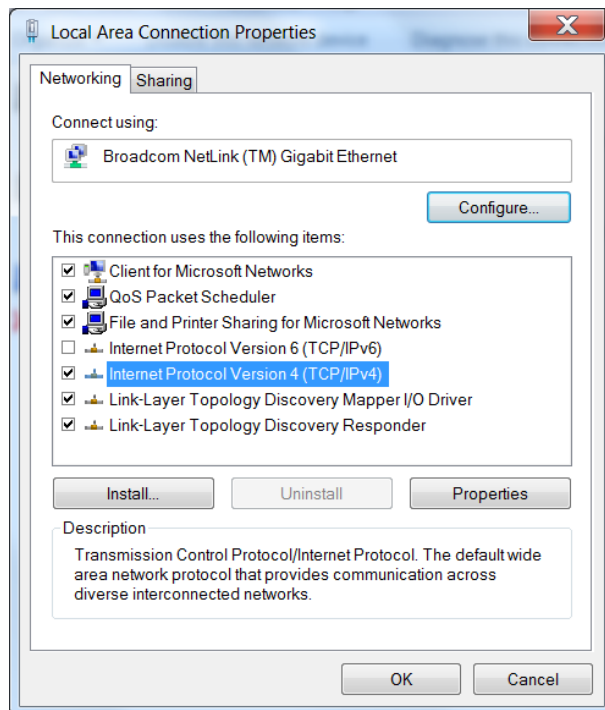


6.3. Communication setup

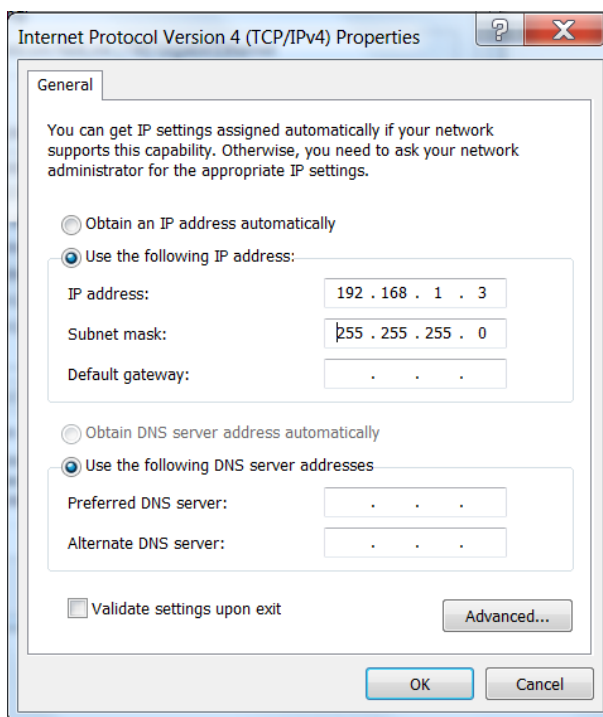
By default TCW210-TH is delivered with the following network settings:

IP address: 192.168.1.2, Subnet Mask: 255.255.255.0, Default Gateway: 192.168.1.1

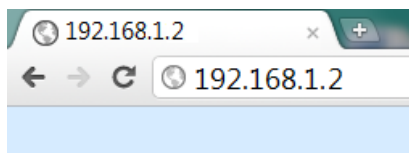
Communication with TCW210-TH can be established by assigning a temporary IP address to the computer. For computers with Windows OS assigning of IP address is made in “Local area connection properties”:



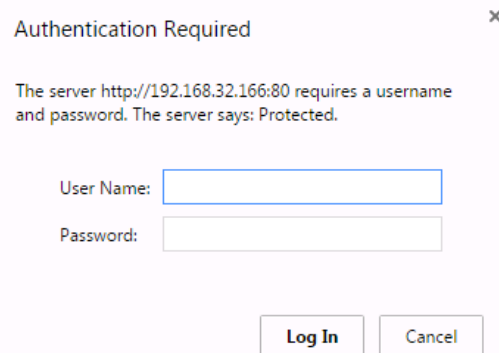
The address should be on the same network - for example 192.168.1.3:



To get access to the web interface, you should type `http://192.168.1.2` into the browser:



If the network settings are correct, the login pop-up window will appear:



All TCW controllers connected to LAN can be easily found by the free tool “TCW discoverer”.

It is available for Win and Mac operating systems and can be downloaded from www.teracomsystems.com.

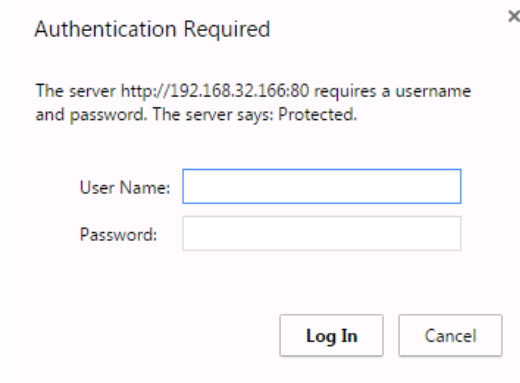
7. Web interface

The WEB interface allows configuration, monitoring, and control. All pages are UTF-8 encoded. For the WEB interface, the device supports HTTP only (HTTPS is not supported).

If the controller is properly addressing, login pop-up window appears.

Authorization data must be entered (by default username=admin, password=admin).

It is recommended to change the username and password to prevent unauthorized access to the controller.



The controller supports a few active session.

7.1. Monitoring

Monitoring page displays the current state of TCW210-TH. It has one data and four graphs tabs.

7.1.1. Data

1-Wire sensors					
Pos	Description	Temperature	Humidity	Dew point	ID
1	S1:TST1xx	23.1 °C	-----	-----	[2867895F07000058]
2	S2	-----	-----	-----	[0000000000000000]
3	S3	-----	-----	-----	[0000000000000000]
4	S4	-----	-----	-----	[0000000000000000]

Modbus sensors						
Pos	Description	Temperature	Humidity	Dew point	ID	Address
5	S5	23.1 °C	-----	-----	[3300A118A1FFFF60]	2
6	S6	22.5 °C	47.8%RH	10.9 °C	[152DB379F9FFFF43]	3
7	S7	-----	-----	-----	[0000000000000000]	0
8	S8	-----	-----	-----	[0000000000000000]	0

The current state of TCW210-TH can be monitored on this page. There are two sections on the page - one for 1-Wire sensors and one for MODBUS RTU sensors.

TCW210-TH supports up to eight sensors. They can be connected to both interfaces in a random ratio, settable in section “Sensors ratio setup” on Setup->Sensors page. By default, the number of MODBUS RTU sensors are 4.

All detected 1-Wire sensors are shown in “1-Wire sensors” section. The sensors should be setup in section “1-Wire sensors setup” on Setup->Sensors page.

Teracom 1-Wire temperature sensors readings are shown in the column “Temperature”, while for dual sensors (TSH2xx) both column “Temperature” and “Humidity” are used. For dual sensors, the parameter Dew point is calculated.

All MODBUS RTU sensors are shown in “Modbus sensors” section. The sensors should be added and set up on Setup->Sensors page.

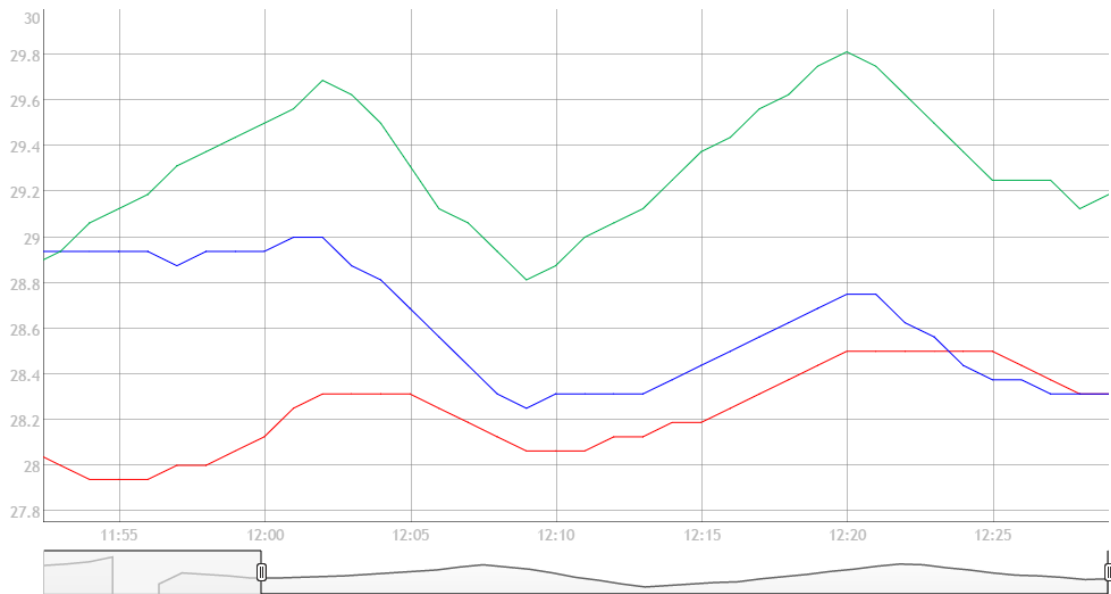
For every sensor, there are a description, value, and ID information. The description length is up to 15 characters. Default descriptions can be changed in Setup->Conditions page.

Dual sensors (humidity-temperature) have the two parameters. For these sensors, Dew point parameter is calculated automatically.

The page can be automatically refreshed on an interval of 0 to 253 seconds. Zero means no automatic refresh. This parameter is set in section Setup->System->Monitoring page automatic refresh. By default, it is 1 second.

7.1.2. Graphs

Every graph page can display up to 4 parameters with up to 2 different dimension.



For every parameter different color can be set. There are a few checkboxes for display modification.

Export of monitored parameters can be made from the page.

7.2. Setup

7.2.1. Network

The network parameters are set on this page.

The controller supports static and dynamic IP addresses.

It is good practice to change the default IP address of the controller immediately after first power-on. This will avoid collisions if many devices are used on the same network.

It may be necessary to clear the arp cache, each time you connect a new device to the network. This is done by typing `arp -d` in the command prompt window of the computer.

The "Hostname" is up to 15 characters. It is shown in the search results of TCW discoverer.

7.2.2. Sensors

7.2.2.1. Sensors ratio setup

Sensors ratio setup
Number of 1Wire sensors
Number of Modbus sensors

The ratio between 1-Wire and MODBUS RTU sensors can be set here. By default, it is 4:4.

7.2.2.2. 1-Wire sensors setup

1-Wire sensors setup

Pos	Description	Temperature	Humidity	ID	Lock
1	S1:TST1xx	23.2°C	-----	[2867895F07000058]	<input type="checkbox"/>
2	S2	-----	-----	[0000000000000000]	<input type="checkbox"/>
3	S3	-----	-----	[0000000000000000]	<input type="checkbox"/>
4	S4	-----	-----	[0000000000000000]	<input type="checkbox"/>

Detection is made either after power on or by the button “Scan for new sensors”. All found sensors are shown in ascending order refer their unique ID number.

It is possible to lock a 1-Wire sensor in a specific position. To do this all sensors should be added one by one. After every addition, a new scan should be made and a newly found sensor should be locked in its position. If all sensors are locked, removing one “in the middle” will not change the positions of other sensors after reset. This option is very useful when TCW210-TH is used as a part of a monitoring and control system managed either by SNMP or HTTP API commands.

7.2.2.3. MODBUS RTU communication setup

Modbus RTU communication setup
Bit rate Scan time-out for a sensor, ms Max scan time: 24700
Parity First address
Stop bits Last address

Found: 4 sensors with following addresses: 1,2,3,4

TCW210-TH supports MODBUS RTU over RS-485 interface. All sensors connected to this interface should work with the same communication settings.

By default, TCW210-TH works with the standard for MODBUS RTU settings – 19200, E, 1.

In the right part of the section, there is a tool for scan the MODBUS RTU interface. To optimize scan time, the appropriate address segment should be set up after this, the button “Save” on the bottom of the page should be pressed.

7.2.2.4. MODBUS RTU sensors

Modbus RTU sensors

Pos	Sensor address	Data type	Data order	Temperature register		Humidity register		Response time-out, ms (10-500) ms
				Address	Raw value	Address	Raw value	
5	<input type="text" value="2"/>	<input type="text" value="float"/>	<input type="text" value="MSW first"/>	<input type="text" value="100"/>	23.2	<input type="text" value=""/>	---	<input type="text" value="100"/>
6	<input type="text" value="3"/>	<input type="text" value="float"/>	<input type="text" value="MSW first"/>	<input type="text" value="100"/>	22.6	<input type="text" value="102"/>	48.0	<input type="text" value="100"/>
7	<input type="text" value="0"/>	<input type="text" value="float"/>	<input type="text" value="LSW first"/>	<input type="text" value=""/>	---	<input type="text" value=""/>	---	<input type="text" value=""/>
8	<input type="text" value="0"/>	<input type="text" value="float"/>	<input type="text" value="LSW first"/>	<input type="text" value=""/>	---	<input type="text" value=""/>	---	<input type="text" value=""/>

[Modbus sensors setup tool](#)

TCW210-TH supports Teracom and third-party MODBUS RTU sensors.

Before to add MODBUS RTU sensors, the user should take care of their address setting. It is not allowed to use two sensors with the same address. It is recommended to scan for new sensors before to make any changes.

For every sensor, an appropriate register address together with the data type and data order should be set. All changes should be saved. If the settings are OK in the columns “Raw value” the right data will be shown.

TCW210-TH supports MODBUS RTU sensors with response time-out between 10 and 500mS. The response time-out for a new sensor is 100mS by default but it is recommended to use minimum response time guaranteed by the sensor’s manufacturer.

The sum of chosen response time-out for every sensor forms the maximum response time-out for the system.

The polling time is the time between two sequential readings of the same sensor. The chosen polling time determines the system's time of reaction. By default, it is 1 second.

Important: The maximum response time-out can’t be lower than the polling time.

7.2.2.5. Sensor setup tool

The link for the tool is available on the bottom of the Modbus RTU sensors paragraph. It can be used for sensor communication setup changes or just to read information from a register.

7.2.2.5.1. Communication setup

The section is similar to the general MODBUS RTU communication setup. The only new field is the sensor address.

The changes of settings in this section are not memorized and don’t change the general settings of TCW210-TH.

Communication setup			
Bit rate	19200	Time-out	100
Parity	even	First address	1
Stop bits	1	Last address	20
		Scan	
MB Address	1	Found: 4 sensors with following addresses: 1,2,3,4	

7.2.2.5.2. Sensor communication register setup

This part of the tool is used for check and change the status of communication registers of the sensor.

Sensor communication register setup			
Bit rate register #	11	Value	19200
Parity, stop register #	12	Value	1
Address register #	10	Value	1 (1 :- 247)
Read		Write	

7.2.2.5.3. Sensor register check

Sensor register check				
Start address	Data type	Number of registers to read	Data order	Row value
100	float	2	MSV first	23.882
Read		---		

This part of the tool is used for general sensor register check.

7.2.3. Conditions

This section is used for parameterization of trigger and alert conditions for 1-Wire and MODBUS RTU sensors.

Sensors										If out of range		
#	Description	Type	Parameter	Min.	Max.	Hys.	Multiplier	Offset	mail	trap	post	
1	S1:TST1xx	1W	Temperature, °C	-40.0	85.0	8.5	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
2	S2	MB	Temperature, °C	-40.0	85.0	8.5	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Humidity, %RH	0.0	100.0	10.0	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Dew point, °C	0.0	25.0	2.5			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
3	S3	MB	Temperature, °C	-40.0	85.0	8.5	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Humidity, %RH	0.0	100.0	10.0	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Dew point, °C	0.0	25.0	2.5			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
4	S4	MB	Temperature, °C	-40.0	85.0	8.5	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Humidity, %RH	0.0	100.0	10.0	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			Dew point, °C	0.0	25.0	2.5			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
5	S5	MB	Temperature, °C	-40.0	85.0	8.5	1.000	0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
6	S6	MB	---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
7	S7	MB	---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
8	S8	MB	---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
			---	---	---	---			<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

Return notification Notification delay (seconds) (0-3600)

For every sensor, a description up to 15 characters can be set.

For all sensors “Offset” field is enabled. The offset is used for simple correction of displayed value.

For all Modbus RTU sensors multiplier is enabled, but for Teracom sensors it should be 1.

For every parameter, there is a field for trigger conditions (“Min”, “Max” and “Hys.”).

“Min” and “Max” indicate the border of the working range for the observed parameter.

A “Max” trigger condition occurs when the value exceeds the trigger set point. A “Min” trigger condition occurs when the value is lower than the trigger set point. In both cases, the monitored parameter goes out of range.

Coming back in range for the observed parameter is considered when the value goes higher than (Min + Hys) or lower than (Max – Hys). Hysteresis (“Hys”) is used to prevent excessively triggering when the value vacillates around trigger point.

Example:

TCW210-TH and TST103 are used to monitoring of room temperature. The wanted minimum temperature is 19°C. The initial temperature is 17°C.

TST100 is assigned to the first position for 1-Wire sensors.

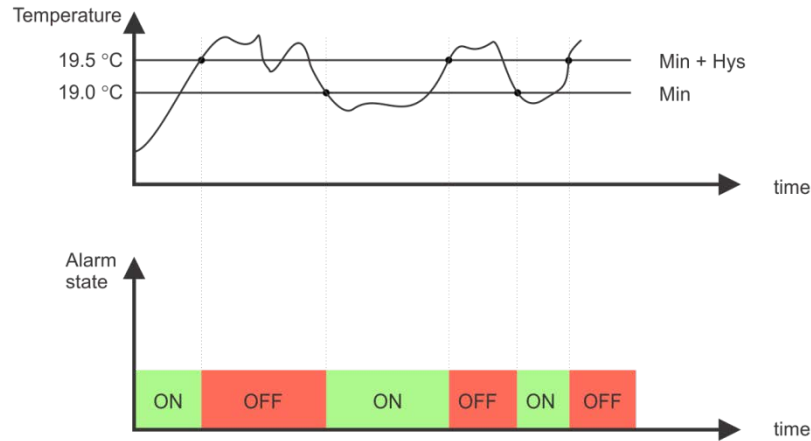
Following parameters are set for Sensor1: Min=19, Max=85 and Hys=0.5.

Sensors										If out of range		
#	Description	Int.	Type	Min.	Max.	Hys.	Multiplier	Offset	mail	trap	post	
1	S1:TST1xx	1W	Temperature, °C	19.0	85.0	0.5		0.00	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

When the controller is switched on, Alarm is immediately activated because the monitored temperature is out of range.

When the temperature reaches 19.5°C (19.0 + 0.5) it goes in range (trigger condition) and Alarm is deactivated.

The temperature falls and when it reached 19°C it goes out of range (trigger and alert conditions). E-mail is sent.

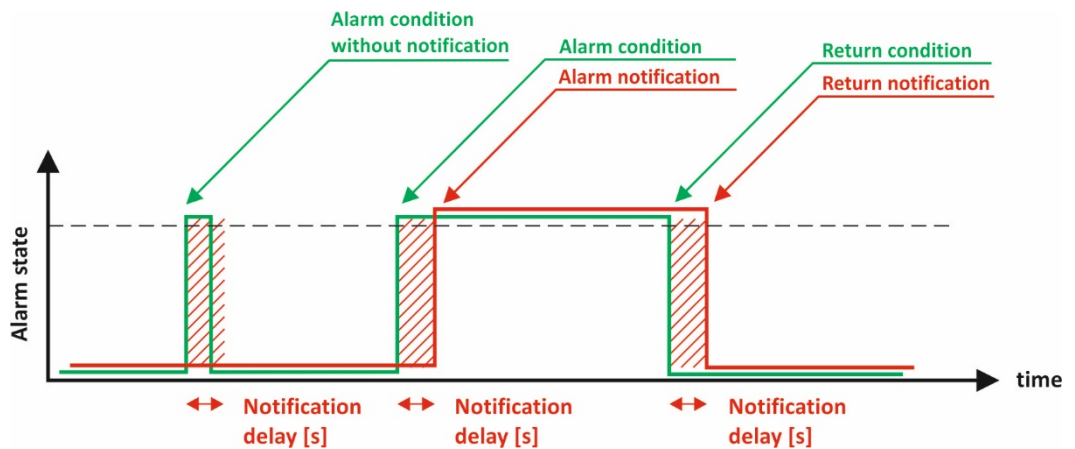


The “Max” value is set far enough from the wanted temperature to avoid trigger/alert conditions around it.

For every sensor, there are 3 independent ways of alert for alarm condition – e-mail, SNMP trap and HTTP/HTTPS post of an XML/JSON file. Each alarm notification method is activated by a checkbox.

Globally for all sensors, there is a checkbox “Return notification”. If this option is chosen there will be notification also when parameter returns in range.

Globally for all sensors, there are “Notification delay” parameter. It is very useful as a filter for short alarm conditions.



7.2.4. System

On this page, some general settings can be made.

7.2.4.1. General

The system name, location, and contact can be used for automatic identification of device via M2M protocols.

General	
System name	<input type="text" value="Name"/>
System location	<input type="text" value="Location"/>
System contact	<input type="text" value="info@teracom.cc"/>

7.2.4.2. WEB access

In this section, WEB access authentication can be deactivated. By default, it is activated with admin/admin authentication details.

HTTP port for WEB access can be changed. This is useful for some routers which don't support different outside/inside ports for port forwarding. By default, HTTP port is 80.

Web access	
Authentication	Enable
HTTP port	80

7.2.4.3. HTTP API

In this section, HTTP API access authentication can be activated/deactivated. By default it is active.

HTTP API	
Authentication	Enable

Authentication details are the same for WEB access. The controller support two types of authentication – see the explanation for HTTP API below.

7.2.4.4. Monitoring page automatic refresh

Monitoring page refresh interval can be set between 0 and 253 seconds. Zero means no automatic refresh.

Monitoring page automatic refresh	
Interval (seconds)	1 (0-253)

7.2.4.5. Display

The unit for observed temperatures can be selected between Celsius and Fahrenheit temperature scales.

If all sensors are attached to the one interface, the other section can be removed from the Monitoring page by the appropriate checkbox.

Display	
Temperature units	Celsius
1-Wire sensors	<input checked="" type="checkbox"/>
Modbus sensors	<input checked="" type="checkbox"/>

7.2.5. Time

Internal RTC (Real Time clock) of the controller can be set either manually or automatically.

Time setup	
Time configuration	NTP server
NTP server IP/URL	time.google.com
Time zone	+3.00
Interval (h)	12
If not found (h)	1
Set time	18.04.2018,16:40:30
Uptime	
Uptime	13days,06:05:00

Current time	18.04.2018,16:40:34
Last updated	18.04.2018,16:40:15
Status	OK
Delay (ms)	43.3mS
Stratum	1

For automatic clock synchronization, the controller supports NTP (Network Time Protocol) and all necessary parameters for automatic synchronization are available in this section.

By default, NTP synchronization is disabled, server – time.google.com, Time zone +0.00 and interval of 12 hours.

7.3. Services

7.3.1. MODBUS

TCW210-TH supports MODBUS TCP/IP over the Ethernet interface.

Modbus TCP/IP	
Modbus	Enable
Port	502

By default, MODBUS TCP/IP is disabled. The standard port for this protocol is 502. The table with the registers' addresses can be found in section 8.3. MODBUS TCP/IP.

7.3.2. SMTP

This page is used to enter valid SMTP settings for email alerts and recipients' addresses.

7.3.2.1. SMTP setup

SMTP setup	
Mail server IP/URL	smtp.mail.yahoo.com
Mail server port	465
Type of encrypted connection	TLS
Sender e-mail	teracom_test@yahoo.com
Username	teracom_test@yahoo.com
Password	*****
<input type="button" value="Test server settings"/>	

Mail server address can be set either by hostname (for example smtp.mail.yahoo.com) or by IP address.

By default, without encrypted connection, SMTP port is 25. Ask ISP if default port doesn't work.

Sender e-mail, username, and password are standard authentication details. For the most SMTP servers, sender e-mail and username are the same.

There is a button for server settings test with feedback. In this test, the sender and recipient of the e-mail are the same.

Transport Layer Security protocol is used for secure communication with public mail servers. TCW210-TH supports TLS 1.0, TLS 1.1 and TLS 1.2 with RSA as a key exchange/agreement and authentication, which ensures successful operation with almost all public servers.

7.3.2.2. Alarm destination

Alarm destinations		
Recipient e-mail	info@teracomsystems.com	<input checked="" type="checkbox"/>
Recipient e-mail		<input type="checkbox"/>
Recipient e-mail		<input type="checkbox"/>
Recipient e-mail		<input type="checkbox"/>
Recipient e-mail		<input type="checkbox"/>
<input type="button" value="Test email"/>		

Up to 5 mail recipients can be set. All they can be activated independently by a checkbox.

7.3.2.3. E-mail details

The subject, body header, body and body footer can be customized. For this customization, a set of keys is used. All they are described on the page.

Email details	
Subject	Att. to #C
Body header	From #N, located at #L
Body	#S,#D=#V#U in #T
Body footer	IP Address:#A, MAC Address:#M
Subject, header and footer variables	Body variables
#N System Name	#D Sensor Description
#L System Location	#V Measured Value
#C System Contact	#U Unit of measured value
#A IP Address of device	#T Time stamp of message
#M MAC address of device	#S Status of parameter-ALARM/NORMAL
#H Hostname	#I ID of message
	#W LoW limit
	#G HiGh limit

7.3.3. SNMP

The TCW210-TH supports SNMP v.2.

In this section, all necessary parameters for proper operation of SNMP can be set.

SNMP setup							
SNMP	Enable ▼						
SNMP port	161						
Read community	public						
Write community	private						
SNMP traps							
IP	192.168.32.32	Port	162	Community	public	Disable ▼	Test
IP	0.0.0.0	Port	162	Community	public	Disable ▼	Test
IP	0.0.0.0	Port	162	Community	public	Disable ▼	Test
IP	0.0.0.0	Port	162	Community	public	Disable ▼	Test
IP	0.0.0.0	Port	162	Community	public	Disable ▼	Test

By default SNMP is disabled, the port is 161, read community is public and write community is private.

In an alarm condition, SNMP trap can be sent up to 5 independent recipients. All they can be with different port and community. There is an independent button for trap test. SNMP traps can be sent if:

- the measured parameter of the sensor goes outside the range;
- restart;
- SW reset.

7.3.4. Logger

The TCW210-TH supports logger for all monitored parameters. The records are made in a circular buffer within the internal flash memory. When the buffer is full, the oldest values are overwritten with the newest ones.

7.3.4.1. Logger

Logger setup	
Logger	Enable
Logger mode	Time mode
Logger record sync	Enable
Log interval (seconds)	60 (10-3600)
Sync to the minute	0 (00-59)
Log interval (minutes)	15

HTTP upload setup	
HTTP upload	Enable
Protocol	https
Server	http(s):// www.teracomsystems:443/temp/TCW220/logs/postlog.php
Upload interval (h)	1h
Sync time	00:00:00

The logger works in three modes – Time, Alarm and Time&Alarm. The mode specifies what initiates a record in the logger’s memory.

In Time mode, records are made periodically on “Log interval” time. In Alarm mode, records are made on every alarm condition. In Time&Alarm mode, a mix of both conditions for records is used.

The log interval determines the time between two log entries. It is good to remember that by reducing the log interval, we increase the resolution, but we also reduce the past period for which we have records.

The logger records can be synchronized with a specific minute in an hour. Synchronization is very useful when monitoring electricity, water, gas meters, etc. The log interval can be chosen from a drop-down menu between 1 and 60 minutes. The field „Sync to the minute“ determines which minute of every hour is used for synchronization. Although any minute can be selected, it is better to use the default value - 00.

Example:

The current settings are:

- Current time = 09:12
- Logger record sync = Enable;
- Sync to the minute = 00;
- Sync interval = 15 minutes.

The settings determine 4 records per hour in **HH:00**, HH:15, HH:30, and HH:45.

The device is powered up.

The first record will be immediately after power-up - 09:12. The next records will be in 09:15, 09:30, 09:45, 10:00, 10:15, etc.

There are two ways to reach the logger records:

- download of the full log file, using “Download full log” in the WEB interface;
- periodical upload the last unsent records to the dedicated HTTP server.

The records are uploaded in CSV file format using HTTP or HTTPS protocol. The HTTPS upload is over TLS 1.0, TLS 1.1 and TLS 1.2 with RSA as a key exchange/agreement and authentication.

The period of the upload can be chosen from the menu between 1 and 24 hours. If you enable this service, take care of the real-time clock (NTP service).

The HTTP server for upload can be domain or IP address but take care about DNS settings.

“Sync time” is a moment in the day when a period of upload is synchronized.

Example:

Current time is 19:31, Upload period is 3 hours and Sync time is 9:00.

To synchronize the logger to 9:00 it means that time for uploads will be: 09:00, 12:00, 15:00, 18:00, 21:00, 24:00, 03:00 and 06:00. The first upload, after enabling the logger in 19:31, will be in 21:00.

The button “Force upload” initiates upload recorded information between previous periodical upload and now.

By default, the logger is disabled.

More about the logger can be found in the Data logger section.

7.3.5. HTTP post

TCW210-TH can periodically upload a file to a dedicated server, using HTTP or HTTPS Post.

The HTTPS is over TLS 1.0, TLS 1.1 and TLS 1.2 with RSA as a key exchange/agreement and authentication.

The posting period is between 10 and 14400 seconds.

The file format can be XML or JSON.

The screenshot shows a configuration window titled "HTTP post setup". It contains several fields and a button:

- HTTP post:** A dropdown menu set to "Enable".
- Data format:** A dropdown menu set to "XML".
- Protocol:** A dropdown menu set to "http".
- Server:** A text input field containing "http(s)://www.teracomsystems.com/TCW210/post/http_post.php".
- Period (seconds):** A text input field containing "60", with a range "(10-14400)" indicated to the right.
- Connect on any alarm:** An unchecked checkbox.
- Key:** A text input field containing "00:00:00:00:00:22".
- Process answer:** A dropdown menu set to "Yes".
- Test HTTP post:** A button located at the bottom left of the configuration area.

In addition to the periodical post, a file can be uploaded at any alarm condition. In this case “Connect on any alarm” should be checked.

The “Key” field value is sent in the XML/JSON and can be used for device identification.

If “Process Answer” option is enabled, the TCW210-TH will process the answer of the remote server. The list of valid commands is described in section “HTTP API commands”.

7.3.6. Cloud

ThingSpeak server is an open data platform and API for the Internet of Things that enables you to collect, store, analyze, visualize, and act on data from sensors.

The primary element of ThingSpeak activity is the channel, which contains API key, channel ID, and eight data fields.

TCW210-TH has four channel sections – Channel 1, Channel 2, Channel 3 and Channel 4.

ThingSpeak setup	
Enable ThingSpeak	<input type="checkbox"/>
Connect on any alarm	<input type="checkbox"/>
Period (sec)	<input type="text" value="300"/>
Link	<input type="text"/>
Channel 1	
Enable	<input type="checkbox"/>
API key	<input type="text"/>
Channel ID	<input type="text" value="1"/>
Field 1	<input type="text" value="S1:TST1xx Temperature"/>
Field 2	<input type="text" value="S2:TSH2xx Temperature"/>
Field 3	<input type="text" value="S2:TSH2xx Temperature"/>
Field 4	<input type="text" value="S4:TST3xx Temperature"/>
Field 5	<input type="text" value="S5:TST3xx Temperature"/>
Field 6	<input type="text" value="S6:TST3xx Temperature"/>
Field 7	<input type="text" value="S7:TSH3xx Temperature"/>
Field 8	<input type="text" value="none"/>
<input type="button" value="Test"/>	

7.3.7. Dynamic DNS

With dynamic DNS can access TCW210-TH from the public Internet without investing in a broadband account that has a static IP address.

TCW210-TH supports the following DNS services – DynDNS, No-IP, and DNS-O-Matric.

Dynamic DNS setup	
Dynamic DNS	<input type="text" value="Enable"/>
Service	<input type="text" value="DynDNS"/>
Hostname	<input type="text" value="tcw210-th.dyndns.org"/>
User	<input type="text" value="teracomtcw"/>
Password	<input type="text" value="*****"/>
Maintainer e-mail	<input type="text" value="teracom_test@yahoo.com"/> <small>The email is required of some providers for client's identification</small>
DDNS last status	The service is disabled.

7.4. Administration

7.4.1. User/Pass

The screenshot displays two sections for user configuration. The first section, titled "Admin access", contains three input fields: "Username" with the value "admin", "Password", and "Confirm password". Below these fields is a "SAVE" button. The second section, titled "User access", also contains three input fields: "Username" with the value "user", "Password", and "Confirm password". Below these fields is another "SAVE" button.

The TCW210-TH supports two users – “Admin” and “User”.

“Admin” has administrative rights.

“User” shall not modify any settings.

The username and password can be up to 31 characters long.

7.4.2. Backup/Restore

TCW210-TH supports backup and restore of all user setting. All settings are saved in XML backup file. This file can be used after this for restore on many devices. This is very useful for multiplying similar settings to a batch of controllers.

The screenshot shows the "Backup/Restore configuration" section. It features a "Select configuration file" label, a "Choose File" button, and the text "No file chosen". Below this are two buttons: "RESTORE" and "BACKUP".

7.4.3. FW update

The TCW210-TH can be updated via the WEB interface.

The screenshot displays the "Firmware update" section. It shows "Current FW version" as "TCW210TH-v1.208". Below this is a "Select FW version" label, a "Choose File" button, and the text "No file chosen". At the bottom of the section is an "UPLOAD" button.

To update the device follow the steps below:

- Go to www.teracomsystems.com and download the latest firmware;
- From Administration->FW update select downloaded .cod file and press “upload” button;
- After the firmware update is completed, the Login page will appear.

Attention! Don’t turn off the power supply during the update. Turning off the power supply will damage the device.

7.5. Logout

The TCW210-TH support multiseSSION, but the good practice is to log out after finish the work.

8. Protocols and API

8.1. SNMP

Simple Network Management Protocol (SNMP) is a standard internet protocol for managing devices on IP networks. In typical uses of SNMP, one or more administrative computers, called managers, monitor and control devices on LAN. Each controlled device, at all times, executes a software component called an agent which reports information via SNMP to the manager.

The TCW210-TH can be configured and monitored through SNMP.

This could be done using every SNMP v.2 compatible program. Parameters that can be changed, are grouped according to their functions in the tables below. To obtain a valid OID number it is necessary to replace the "x" symbol with "1.3.6.1.4.1.38783".

To save the changes configurationSaved (OID x.2.3.5.0) should be set to "1".

product

OID	Name	Access	Description	Syntax
x.4.1.1.0	name	read-only	Device name	DisplayString
x.4.1.2.0	version	read-only	Firmware version	DisplayString
x.4.1.3.0	date	read-only	Release date	DateAndTime

setup -> network

OID	Name	Access	Description	Syntax
x.4.2.1.1.0	deviceID	read-only	Device ID (default MAC address)	MacAddress
x.4.2.1.2.0	hostName	read-only	Hostname	DisplayString
x.4.2.1.3.0	deviceIP	read-only	Device IP address	IpAddress

setup -> io -> sensorsSetup -> sensor1setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.1.1.0	s1description	read-write	Sensor 1 description	DisplayString
x.4.2.2.1.1.2.1.0	s11MAXInt	read-write	S11 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.1.2.2.0	s11MINInt	read-write	S11 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.1.2.3.0	s11HYSTInt	read-write	S11 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.1.3.1.0	s12MAXInt	read-write	S12 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.1.3.2.0	s12MINInt	read-write	S12 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.1.3.3.0	s12HYSTInt	read-write	S12 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.1.4.1.0	s13MAXInt	read-write	S13 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.1.4.2.0	S13MINInt	read-write	S13 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.1.4.3.0	s13HYSTInt	read-write	S13 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor2setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.2.1.0	s2description	read-write	Sensor2 description	DisplayString
x.4.2.2.1.2.2.1.0	s21MAXInt	read-write	s21 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.2.2.2.0	S21MINInt	read-write	S21 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.2.2.3.0	S21HYSTInt	read-write	S21 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.2.3.1.0	S22MAXInt	read-write	S22 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.2.3.2.0	S22MINInt	read-write	S22 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.2.3.3.0	S22HYSTInt	read-write	S22 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.2.4.1.0	S23MAXInt	read-write	S23 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.2.4.2.0	S23MINInt	read-write	S23 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.2.4.3.0	S23HYSTInt	read-write	S23 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor3setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.3.1.0	S3description	read-write	Sensor 3 description	DisplayString
x.4.2.2.1.3.2.1.0	S31MAXInt	read-write	S31 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.3.2.2.0	S31MINInt	read-write	S31 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.3.2.3.0	S31HYSTInt	read-write	S31 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.3.3.1.0	S32MAXInt	read-write	S32 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.3.3.2.0	S32MINInt	read-write	S32 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.3.3.3.0	S32HYSTInt	read-write	S32 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.3.4.1.0	S33MAXInt	read-write	S33 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.3.4.2.0	S33MINInt	read-write	S33 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.3.4.3.0	S33HYSTInt	read-write	S33 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor4setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.4.1.0	S4description	read-write	Sensor 4 description	DisplayString
x.4.2.2.1.4.2.1.0	S41MAXInt	read-write	S41 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.4.2.2.0	S41MINInt	read-write	S41 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.4.2.3.0	S41HYSTInt	read-write	S41 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.4.3.1.0	S42MAXInt	read-write	S42 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.4.3.2.0	S42MINInt	read-write	S42 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.4.3.3.0	S42HYSTInt	read-write	S42 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.4.4.1.0	S43MAXInt	read-write	S43 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.4.4.2.0	S43MINInt	read-write	S43 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.4.4.3.0	S43HYSTInt	read-write	S43 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor5setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.5.1.0	S5description	read-write	Sensor 5 description	DisplayString
x.4.2.2.1.5.2.1.0	S51MAXInt	read-write	S51 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.5.2.2.0	S51MINInt	read-write	S51 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.5.2.3.0	S51HYSTInt	read-write	S51 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.5.3.1.0	S52MAXInt	read-write	S52 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.5.3.2.0	S52MINInt	read-write	S52 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.5.3.3.0	S52HYSTInt	read-write	S52 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.5.4.1.0	S53MAXInt	read-write	S53 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.5.4.2.0	S53MINInt	read-write	S53 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.5.4.3.0	S53HYSTInt	read-write	S53 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor6setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.6.1.0	S6description	read-write	Sensor 6 description	DisplayString
x.4.2.2.1.6.2.1.0	S61MAXInt	read-write	S61 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.6.2.2.0	S61MINInt	read-write	S61 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.6.2.3.0	S61HYSTInt	read-write	S61 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.6.3.1.0	S62MAXInt	read-write	S62 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.6.3.2.0	S62MINInt	read-write	S62 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.6.3.3.0	S62HYSTInt	read-write	S62 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.6.4.1.0	S63MAXInt	read-write	S63 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.6.4.2.0	S63MINInt	read-write	S63 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.6.4.3.0	S63HYSTInt	read-write	S63 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor7setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.7.1.0	S7description	read-write	Sensor 7 description	DisplayString
x.4.2.2.1.7.2.1.0	S71MAXInt	read-write	S71 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.7.2.2.0	S71MINInt	read-write	S71 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.7.2.3.0	S71HYSTInt	read-write	S71 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.7.3.1.0	S72MAXInt	read-write	S72 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.7.3.2.0	S72MINInt	read-write	S72 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.7.3.3.0	S72HYSTInt	read-write	S72 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.7.4.1.0	S73MAXInt	read-write	S73 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.7.4.2.0	S73MINInt	read-write	S73 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.7.4.3.0	S73HYSTInt	read-write	S73 hysteresis value x1000 in Integer format	Integer32

setup -> io -> sensorsSetup -> sensor8setup

OID	Name	Access	Description	Syntax
x.4.2.2.1.8.1.0	S8description	read-write	Sensor 8 description	DisplayString
x.4.2.2.1.8.2.1.0	S81MAXx10Int	read-write	S81 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.8.2.2.0	S81MINx10Int	read-write	S81 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.8.2.3.0	S81HYSTx10Int	read-write	S81 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.8.3.1.0	S82MAXx10Int	read-write	S82 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.8.3.2.0	S82MINx10Int	read-write	S82 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.8.3.3.0	S82HYSTx10Int	read-write	S82 hysteresis value x1000 in Integer format	Integer32
x.4.2.2.1.8.4.1.0	S83MAXx10Int	read-write	S83 maximum value x1000 in Integer format	Integer32
x.4.2.2.1.8.4.2.0	S83MINx10Int	read-write	S83 minimum value x1000 in Integer format	Integer32
x.4.2.2.1.8.4.3.0	S83HYSTx10Int	read-write	S83 hysteresis value x1000 in Integer format	Integer32

monitorNcontrol -> sensors -> sensor1

OID	Name	Access	Description	Syntax
x.4.3.1.1.1.0	s11Int	read-only	S11 value x1000 in Integer format	Integer32
x.4.3.1.1.2.0	s12Int	read-only	S12 value x1000 in Integer format	Integer32
x.4.3.1.1.3.0	s13Int	read-only	S13 value x1000 in Integer format	Integer32
x.4.3.1.1.4.0	s1ID	read-only	S1 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor2

OID	Name	Access	Description	Syntax
x.4.3.1.2.1.0	s21Int	read-only	S21 value x1000 in Integer format	Integer32
x.4.3.1.2.2.0	s22Int	read-only	S22 value x1000 in Integer format	Integer32
x.4.3.1.2.3.0	s23Int	read-only	S23 value x1000 in Integer format	Integer32
x.4.3.1.2.4.0	s2ID	read-only	S2 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor3

OID	Name	Access	Description	Syntax
x.4.3.1.3.1.0	s31Int	read-only	S31 value x1000 in Integer format	Integer32
x.4.3.1.3.2.0	s32Int	read-only	S32 value x1000 in Integer format	Integer32
x.4.3.1.3.3.0	s3ID	read-only	S3 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor4

OID	Name	Access	Description	Syntax
x.4.3.1.4.1.0	s41Int	read-only	S41 value x1000 in Integer format	Integer32
x.4.3.1.4.2.0	s42Int	read-only	S42 value x1000 in Integer format	Integer32
x.4.3.1.4.3.0	s43Int	read-only	S43 value x1000 in Integer format	Integer32
x.4.3.1.4.3.0	s4ID	read-only	S4 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor5

OID	Name	Access	Description	Syntax
x.4.3.1.5.1.0	s51Int	read-only	S51 value x1000 in Integer format	Integer32
x.4.3.1.5.2.0	s52Int	read-only	S52 value x1000 in Integer format	Integer32
x.4.3.1.5.3.0	s53Int	read-only	S53 value x1000 in Integer format	Integer32
x.4.3.1.5.4.0	s5ID	read-only	S5 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor6

OID	Name	Access	Description	Syntax
x.4.3.1.6.1.0	s61Int	read-only	S61 value x1000 in Integer format	Integer32
x.4.3.1.6.2.0	s62Int	read-only	S62 value x1000 in Integer format	Integer32
x.4.3.1.6.3.0	s63Int	read-only	S63 value x1000 in Integer format	Integer32
x.4.3.1.6.4.0	s6ID	read-only	S6 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor7

OID	Name	Access	Description	Syntax
x.4.3.1.7.1.0	s71Int	read-only	S71 value x1000 in Integer format	Integer32
x.4.3.1.7.2.0	s72Int	read-only	S72 value x1000 in Integer format	Integer32
x.4.3.1.7.3.0	s73Int	read-only	S73 value x1000 in Integer format	Integer32
x.4.3.1.7.4.0	s7ID	read-only	S7 ID value	OCTET STRING (SIZE (16))

monitorNcontrol -> sensors -> sensor8

OID	Name	Access	Description	Syntax
x.4.3.1.8.1.0	s81Int	read-only	S81 value x1000 in Integer format	Integer32
x.4.3.1.8.2.0	s82Int	read-only	S82 value x1000 in Integer format	Integer32
x.4.3.1.8.3.0	s83Int	read-only	S83 value x1000 in Integer format	Integer32
x.4.3.1.8.4.0	s8ID	read-only	S8 ID value	OCTET STRING (SIZE (16))

monitorNcontrol

OID	Name	Access	Description	Syntax
x.4.3.5.0	configurationSaved	read-write	Configuration save status SAVED/UNSAVED	INTEGER { unsaved(0), saved(1) }
x.4.3.6.0	restartDevice	read-write	Restart Device	INTEGER { cancel(0), restart(1) }
x.4.3.7.0	temperatureUnit	read-only	Unit of the all temperature values	INTEGER { celcius(0), fahrenheit(1) }
x.4.3.8.0	hardwareErr	read-only	Hardware Error	INTEGER { noErr(0), owErr(1), hwErr(2) }

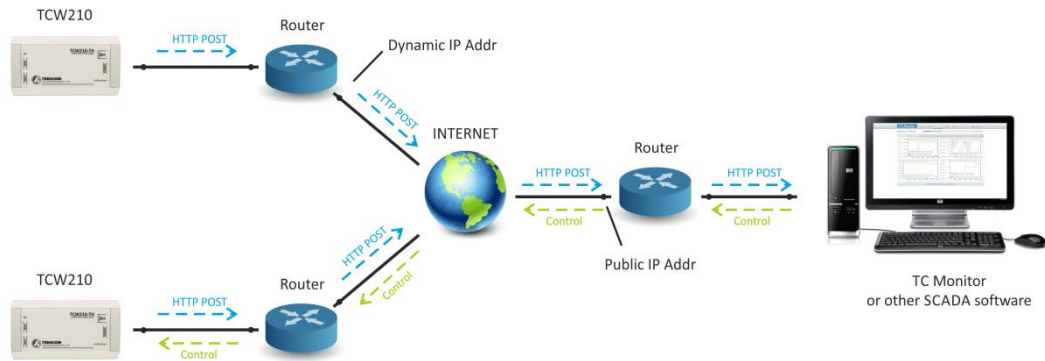
8.2. HTTP API

8.2.1. HTTP Post

TCW210-TH can execute HTTP/HTTPS Post to upload XML/JSON file to a dedicated server.

This functionality is very useful if the controller is behind the router without public IP address or the user don't have access to router configuration. The server should have a public IP address.

The typical monitoring application is shown in the picture below:



HTTP/HTTPS post can be sent periodically or periodically plus on an alarm condition.

To test HTTP/HTTPS Post follow the steps below:

- Save following code like post.php:

```
<?php
define("FILENAME", 'status.xml');
define("FOLDER", "");
define("SEPARATOR", "");
define("STR_SUCCESS", 'set FIN');
define("STR_ERROR", 'error');

if($_SERVER['REQUEST_METHOD'] == 'POST'){
    $datePrefix = date('YmdHis', strtotime('now'));
    $pathname = FOLDER.SEPARATOR.$datePrefix.'.'.FILENAME;
    $postdata = file_get_contents("php://input");
    $handle = fopen($pathname, 'w+');
    $content = var_export($postdata, true);
    fwrite($handle, substr($content, 1, strlen($content)-2));
    fclose($handle);
    echo (($handle === false) ? STR_ERROR : STR_SUCCESS)."\r\n";
}
else {
    echo "The PHP script is working!";
}
?>
```

- Copy the post.php file on a public web server with PHP support. To verify that the script is working properly, you can type the URL in your web browser (for example www.yourserverURL.com/post.php). If all is OK, a web page with “The PHP script is working!” will be shown.
- Set the controller to send an HTTP/HTTPS POST to your web server. Enter the address (yourserverURL.com/post.php) in the URL field. Click on “Test HTTP Post” button.

- If the HTTP/HTTPS POST is received and processed, “OK” will be shown close to the button. Along with this, an XML file will be created in the same directory, where post.php is located. The file name will contain time information and looks like 20171120103318_status.xml.

8.2.2. HTTP Get

HTTP Get can be used to monitor TCW210-TH via XML or JSON files. The format is as follows:

http://device.ip.address/status.xml

http://device.ip.address/status.json

See sections **8.2.4 XML file structure** and **8.2.5 JSON file structure** for details of files.

HTTP Get can be sent at any time to TCW210-TH if it is on the same network or it has appropriate routing.

If there isn't direct access to the device, HTTP Get can be sent immediately after HTTP Post receiving from the same device.

8.2.2.1. Commands

All command used with HTTP Post can be used also with HTTP Get. The right format is:

http://device.ip.address/status.xml?yyy=xxx

Where:

yyy is the command;

xxx is the parameter.

Example:

http://device.ip.address/status.xml?pper=120 will set post period of 120 sec.

8.2.2.2. HTTP GET authentication

If HTTP API authentication is enabled, basic access authentication is required to access the status.xml file. The format of the command is shown in the table below:

XML/HTTP API authentication	Format
enabled	http://device.ip.address/status.xml?a=uuuu:pppp
disabled	http://device.ip.address/status.xml

Example:

http://device.ip.address/status.xml?a=admin:admin&pper=120 will set post period of 120 sec in case the username=admin and pass=admin

8.2.3. List of HTTP API commands

Command	Description
snpt=30.0	Set Min of sensor to 30.0 (p is 1,2,3,4,5,6,7 or 8 for the respective sensor t is 1 or 2 for the respective parameter of sensor) sn12=30.0 will set Min for sensor 1, parameter 2
sxpt=40.0	Set Max of sensor to 40.0 (p is 1,2,3,4,5,6,7 or 8 for the respective sensor t is 1 or 2 for the respective parameter of sensor) sx42=40.0 will set Min for sensor 4, parameter 2
sypt=2.0	Set Hys of sensor to 2.0 (p is 1,2,3,4,5,6,7 or 8 for the respective sensor t is 1 or 2 for the respective parameter of sensor) sy81=2.0 will set Hys for sensor 8, parameter 1
delsen=xxxx	Notification delay for sensors (xxxx is between 0 and 3600)
pmet=x	Enable/disable HTTP Post - 0 disable, 1 enable

dataf=x	Data format XML/JSON for HHTP Post – 0 XML, 1 JSON
pushtls=x	http(s) protocol, where x is 0 for http and 1 for https
purl=yyy	URL for HTTP Post to Server 1, where yyy is a full path to php file. Example: purl=212.25.45.120:30181/xampp/test/posttest.php
pper=x	HTTP Post period in seconds (x is between 10 and 14400)
dk=xxx	HTTP Post key – xxx is up to 17 characters
pans=x	HTTP Post process answer – 0 No, 1 Yes
FIN	Terminate session. (It works with HTTP/HTTPS Post, but not with HTTP Get.)

8.2.4. XML file structure

```

<Monitor>
  <DeviceInfo>
    <DeviceName>TCW210-TH</DeviceName>
    <HostName>TCW210TH</HostName>
    <ID>5C:32:C5:00:69:01</ID>
    <FwVer>TCW210TH-v1.223</FwVer>
    <MnInfo>www.teracomsystems.com</MnInfo>
    <SysContact>info@teracomsystems.com</SysContact>
    <SysName>SysName</SysName>
    <SysLocation>SysLocation</SysLocation>
  </DeviceInfo>
  <S>
    <S1>
      <description>1</description>
      <id>2867895F07000058</id>
      <SenType>1W</SenType>
      <addr>---</addr>
      <item1>
        <value>23.6</value>
        <unit>°C</unit>
        <alarm>0</alarm>
        <min>-40.0</min>
        <max>85.0</max>
        <hys>8.5</hys>
      </item1>
      <item2>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
      </item2>
      <item3>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
      </item3>
    </S1>
    <S2>
      <description>S2</description>
      <id>15AA3168E6FFFC6</id>
      <SenType>MB</SenType>
      <addr>2</addr>
      <item1>
        <value>23.4</value>
        <unit>°C</unit>
        <alarm>0</alarm>
        <min>-40.0</min>
        <max>85.0</max>
        <hys>8.5</hys>
    </S2>
  </S>
</Monitor>

```

```

</item1>
<item2>
  <value>35.5</value>
  <unit>%RH</unit>
  <alarm>0</alarm>
  <min>0.0</min>
  <max>100.0</max>
  <hys>10.0</hys>
</item2>
<item3>
  <value>7.3</value>
  <unit>°C</unit>
  <alarm>0</alarm>
  <min>0.0</min>
  <max>25.0</max>
  <hys>2.5</hys>
</item3>
</S2>
<S3>
  <description>S3</description>
  <id>152DB379F9FFFF43</id>
  <SenType>MB</SenType>
  <addr>3</addr>
  <item1>
    <value>23.0</value>
    <unit>°C</unit>
    <alarm>0</alarm>
    <min>-40.0</min>
    <max>85.0</max>
    <hys>8.5</hys>
  </item1>
  <item2>
    <value>36.4</value>
    <unit>%RH</unit>
    <alarm>0</alarm>
    <min>0.0</min>
    <max>100.0</max>
    <hys>10.0</hys>
  </item2>
  <item3>
    <value>7.3</value>
    <unit>°C</unit>
    <alarm>0</alarm>
    <min>0.0</min>
    <max>25.0</max>
    <hys>2.5</hys>
  </item3>
</S3>
<S4>
  <description>S4</description>
  <id>15DAEEA0D2FFFF0A</id>
  <SenType>MB</SenType>
  <addr>4</addr>
  <item1>
    <value>23.8</value>
    <unit>°C</unit>
    <alarm>0</alarm>
    <min>-40.0</min>
    <max>85.0</max>
    <hys>8.5</hys>
  </item1>
  <item2>
    <value>32.2</value>
    <unit>%RH</unit>
    <alarm>0</alarm>
    <min>0.0</min>
    <max>100.0</max>
    <hys>10.0</hys>
  </item2>
  <item3>
    <value>6.2</value>
    <unit>°C</unit>
    <alarm>0</alarm>
    <min>0.0</min>
    <max>25.0</max>
    <hys>2.5</hys>
  </item3>

```

```

</S4>
<S5>
  <description>S5</description>
  <id>3300A118A1FFFF60</id>
  <SenType>MB</SenType>
  <addr>1</addr>
  <item1>
    <value>23.9</value>
    <unit>°C</unit>
    <alarm>0</alarm>
    <min>-40.0</min>
    <max>85.0</max>
    <hys>8.5</hys>
  </item1>
  <item2>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item2>
  <item3>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item3>
</S5>
<S6>
  <description>S6</description>
  <id>0000000000000000</id>
  <SenType>MB</SenType>
  <addr>0</addr>
  <item1>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item1>
  <item2>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item2>
  <item3>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item3>
</S6>
<S7>
  <description>S7</description>
  <id>0000000000000000</id>
  <SenType>MB</SenType>
  <addr>0</addr>
  <item1>
    <value>---</value>
    <unit>---</unit>
    <alarm>0</alarm>
    <min>---</min>
    <max>---</max>
    <hys>---</hys>
  </item1>
  <item2>
    <value>---</value>
    <unit>---</unit>

```

```

        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
    </item2>
    <item3>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
    </item3>
</S7>
<S8>
    <description>S8</description>
    <id>0000000000000000</id>
    <SenType>MB</SenType>
    <addr>0</addr>
    <item1>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
    </item1>
    <item2>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
    </item2>
    <item3>
        <value>---</value>
        <unit>---</unit>
        <alarm>0</alarm>
        <min>---</min>
        <max>---</max>
        <hys>---</hys>
    </item3>
</S8>
</S>
<HTTPPush>
    <Key/>
    <PushPeriod>300</PushPeriod>
</HTTPPush>
<hwerr/>
<Alarmed>0</Alarmed>
<Scannig/>
<Time>
    <Date>28.01.2019</Date>
    <Time>15:59:43</Time>
</Time>
</Monitor>

```

Where:

<value>---</value> and <unit>---</unit> means no sensor on this position;

<alarm>1</alarm> means there is trigger condition.

8.2.5. JSON file structure

```
{
  "Monitor": {
    "DeviceInfo": {
      "DeviceName": "TCW210-TH",
      "HostName": "TCW210TH",
      "ID": "5C:32:C5:00:69:01",
      "FwVer": "TCW210TH-v1.223",
      "MnflInfo": "www.teracomsystems.com",
      "SysContact": "info@teracomsystems.com",
      "SysName": "SysName",
      "SysLocation": "SysLocation"
    },
    "S": {
      "S1": {
        "description": "1",
        "id": "2867895F07000058",
        "SenType": "1W",
        "addr": "---",
        "item1": {
          "value": "23.7",
          "unit": "°C",
          "alarm": "0",
          "min": "-40.0",
          "max": "85.0",
          "hys": "8.5"
        },
        "item2": {
          "value": "---",
          "unit": "---",
          "alarm": "0",
          "min": "---",
          "max": "---",
          "hys": "---"
        },
        "item3": {
          "value": "---",
          "unit": "---",
          "alarm": "0",
          "min": "---",
          "max": "---",
          "hys": "---"
        }
      },
      "S2": {
        "description": "S2",
        "id": "15AA3168E6FFFFC6",
        "SenType": "MB",
        "addr": "2",
        "item1": {
          "value": "23.5",
          "unit": "°C",
          "alarm": "0",
          "min": "-40.0",
          "max": "85.0",
          "hys": "8.5"
        },
        "item2": {
          "value": "35.6",
          "unit": "%RH",
          "alarm": "0",
          "min": "0.0",
          "max": "100.0",
          "hys": "10.0"
        },
        "item3": {
          "value": "7.4",
          "unit": "°C",
          "alarm": "0",
          "min": "0.0",
          "max": "25.0",
          "hys": "2.5"
        }
      },
      "S3": {
        "description": "S3",
```



```

"id": "152DB379F9FFFF43",
"SenType": "MB",
"addr": "3",
"item1": {
  "value": "23.2",
  "unit": "°C",
  "alarm": "0",
  "min": "-40.0",
  "max": "85.0",
  "hys": "8.5"
},
"item2": {
  "value": "36.6",
  "unit": "%RH",
  "alarm": "0",
  "min": "0.0",
  "max": "100.0",
  "hys": "10.0"
},
"item3": {
  "value": "7.6",
  "unit": "°C",
  "alarm": "0",
  "min": "0.0",
  "max": "25.0",
  "hys": "2.5"
}
},
"S4": {
  "description": "S4",
  "id": "15DAEEA0D2FFFF0A",
  "SenType": "MB",
  "addr": "4",
  "item1": {
    "value": "23.8",
    "unit": "°C",
    "alarm": "0",
    "min": "-40.0",
    "max": "85.0",
    "hys": "8.5"
  },
  "item2": {
    "value": "32.7",
    "unit": "%RH",
    "alarm": "0",
    "min": "0.0",
    "max": "100.0",
    "hys": "10.0"
  },
  "item3": {
    "value": "6.4",
    "unit": "°C",
    "alarm": "0",
    "min": "0.0",
    "max": "25.0",
    "hys": "2.5"
  }
},
"S5": {
  "description": "S5",
  "id": "3300A118A1FFFF60",
  "SenType": "MB",
  "addr": "1",
  "item1": {
    "value": "23.8",
    "unit": "°C",
    "alarm": "0",
    "min": "-40.0",
    "max": "85.0",
    "hys": "8.5"
  },
  "item2": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",

```

```

    "hys": "---"
  },
  "item3": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  }
},
"S6": {
  "description": "S6",
  "id": "0000000000000000",
  "SenType": "MB",
  "addr": "0",
  "item1": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  },
  "item2": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  },
  "item3": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  }
},
"S7": {
  "description": "S7",
  "id": "0000000000000000",
  "SenType": "MB",
  "addr": "0",
  "item1": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  },
  "item2": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  },
  "item3": {
    "value": "---",
    "unit": "---",
    "alarm": "0",
    "min": "---",
    "max": "---",
    "hys": "---"
  }
},
"S8": {
  "description": "S8",
  "id": "0000000000000000",
  "SenType": "MB",
  "addr": "0",
  "item1": {

```

```
        "value": "---",
        "unit": "---",
        "alarm": "0",
        "min": "---",
        "max": "---",
        "hys": "---"
    },
    "item2": {
        "value": "---",
        "unit": "---",
        "alarm": "0",
        "min": "---",
        "max": "---",
        "hys": "---"
    },
    "item3": {
        "value": "---",
        "unit": "---",
        "alarm": "0",
        "min": "---",
        "max": "---",
        "hys": "---"
    }
}
},
"HTTPPush": {
    "Key": "",
    "PushPeriod": "300"
},
"hwerr": "",
"Alarmed": "0",
"Scannig": "",
"Time": {
    "Date": "28.01.2019",
    "Time": "16:44:16"
}
}
}
```

8.3. MODBUS TCP/IP

MODBUS TCP/IP protocol is originally published by Modicon in 1979. It is used to establish master-slave/client-server communication between intelligent devices. MODBUS TCP/IP is often used to connect a supervisory computer with remote units in supervisory control and data acquisition (SCADA) systems.

8.3.1. Codes and answers

8.3.1.1. Read Holding Registers (FC=03)

Request

This command is requesting the content of holding registers 100.

03 0064 0002

03: The Function Code 3 (read Holding Registers)

0064: The Data Address of the first register requested (0064 hex = 100)

0002: The total number of registers requested. (read 2 registers each 2 byte = 4 bytes)

Response

03 04 4296 8000

03: The Function Code 3 (read Analog Output Holding Registers)

04: The number of data bytes to follow (2 registers x 2 bytes each = 4 bytes)

4296 8000: 4 bytes value

All holding registers with float value are sent in big-endian.

In the example, the above value of 75.25 is sent.

Request

This command is requesting the content of holding registers 200.

03 00C8 0020

03: Function Code 3 (read Holding Registers)

00C8: The Data Address of the first register requested (00C8 hex = 200)

0020: The total number of registers requested (read 32 registers each 2 byte = 64 bytes)

Response

03 40 5365 6E73 6F72 3100 0000

03: Function Code 3 (read Analog Output Holding Registers)

40: The number of data bytes to follow (32 registers x 2 bytes each = 64 bytes)

5365 6e73 6f72 3100 0000 0000 0000 0000 0000 0000 0000 0000 0000

0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000

0000 0000 0000 0000 0000 0000 0000 0000: 64 bytes value

All holding registers with strings are sent in big-endian.

The answer is padded with 0.

In the example above string "Sensor1" is sent.

8.3.1.2. Exception codes

All exceptions are signaled by adding 0x80 to the function code of the request, and following this byte by a single reason byte for example as follows:

01 Illegal function

The function code received in the query is not an allowable action for the controller.

02 Illegal data address

The data address received in the query is not an allowable address for the slave. More specifically, the combination of the reference number and transfer length is invalid. For a controller with 100 registers, a request with offset 96 and length 4 would succeed, a request with offset 96 and length 5 will generate exception 02.

8.3.2. Address table

Parameter	FC	Address (Decimal)	Data size
Number of installed sensors	03	99	16-bit Integer
Read Sensor 11	03	100	32-bit Float
Read Sensor 12	03	102	32-bit Float
Read Sensor 13	03	104	32-bit Float
Read Sensor 21	03	106	32-bit Float
Read Sensor 22	03	108	32-bit Float
Read Sensor 23	03	110	32-bit Float
Read Sensor 31	03	112	32-bit Float
Read Sensor 32	03	114	32-bit Float
Read Sensor 33	03	116	32-bit Float
Read Sensor 41	03	118	32-bit Float
Read Sensor 42	03	120	32-bit Float
Read Sensor 43	03	122	32-bit Float
Read Sensor 51	03	124	32-bit Float
Read Sensor 52	03	126	32-bit Float
Read Sensor 53	03	128	32-bit Float
Read Sensor 61	03	130	32-bit Float
Read Sensor 62	03	132	32-bit Float
Read Sensor 63	03	134	32-bit Float
Read Sensor 71	03	136	32-bit Float
Read Sensor 72	03	138	32-bit Float
Read Sensor 73	03	140	32-bit Float
Read Sensor 81	03	142	32-bit Float
Read Sensor 82	03	144	32-bit Float
Read Sensor 83	03	146	32-bit Float

Sensor 1 Description	03	5400	64 bytes UTF-8
Sensor 2 Description	03	5432	64 bytes UTF-8
Sensor 3 Description	03	5464	64 bytes UTF-8
Sensor 4 Description	03	5496	64 bytes UTF-8
Sensor 5 Description	03	5528	64 bytes UTF-8
Sensor 6 Description	03	5560	64 bytes UTF-8
Sensor 7 Description	03	5592	64 bytes UTF-8
Sensor 8 Description	03	5624	64 bytes UTF-8

Sensor 11 Dimension	03	9800	64 bytes UTF-8
Sensor 12 Dimension	03	9832	64 bytes UTF-8
Sensor 13 Dimension	03	9864	64 bytes UTF-8
Sensor 21 Dimension	03	9896	64 bytes UTF-8
Sensor 22 Dimension	03	9928	64 bytes UTF-8
Sensor 23 Dimension	03	9960	64 bytes UTF-8
Sensor 31 Dimension	03	9992	64 bytes UTF-8
Sensor 32 Dimension	03	10024	64 bytes UTF-8
Sensor 33 Dimension	03	10056	64 bytes UTF-8
Sensor 41 Dimension	03	10088	64 bytes UTF-8
Sensor 42 Dimension	03	10120	64 bytes UTF-8
Sensor 43 Dimension	03	10152	64 bytes UTF-8
Sensor 51 Dimension	03	10184	64 bytes UTF-8
Sensor 52 Dimension	03	10216	64 bytes UTF-8
Sensor 53 Dimension	03	10248	64 bytes UTF-8
Sensor 61 Dimension	03	10280	64 bytes UTF-8
Sensor 62 Dimension	03	10312	64 bytes UTF-8
Sensor 63 Dimension	03	10344	64 bytes UTF-8
Sensor 71 Dimension	03	10376	64 bytes UTF-8
Sensor 72 Dimension	03	10408	64 bytes UTF-8
Sensor 73 Dimension	03	10440	64 bytes UTF-8
Sensor 81 Dimension	03	10472	64 bytes UTF-8
Sensor 82 Dimension	03	10504	64 bytes UTF-8
Sensor 83 Dimension	03	10536	64 bytes UTF-8

8.4. MODBUS RTU

8.4.1. Communication parameters

For MODBUS RTU, TCW210-TH supports the following communication parameters:

- Baud rate – 2400, 4800, 9600, 19200, 38400, or 57600;
- Data bits – 8;
- Stop bits – 1 or 2;
- Parity – Odd or Even;

As factory default communication parameters the device uses standard ones for MODBUS RTU:

- Baud rate – 19200;
- Data bits – 8;
- Stop bits – 1;
- Parity – Even;

8.4.2. Teracom sensors update tool

TCW210-TH supports Teracom sensor FW update tool.

The tool is available at <http://device.ip.address/teracom485.htm>.

Attention! To make any changes to MODBUS RTU sensor it should be alone on the RS-485 bus.

8.4.2.1. Sensor settings

Sensor settings	
Current address	1
Sensor info	TST3xx-v2.12
ID	[3300A118A1FFFF60]
<input type="button" value="Scan"/>	

The tool works with the current MODBUS RTU communication parameters.

To avoid collisions the good practice is to set TCW210-TH and the sensor with the factory default MODBUS RTU communication parameters. This will ensure smooth operation. The default MODBUS RTU communication parameters for TCW210-TH are described in 8.4.1. Communication parameters.

Before to make any changes it is strongly recommended to scan for sensor settings. This will inform about the current FW version of the sensor but also will check if the sensor is alone on the bus.

8.4.2.2. Sensor FW update

Sensor FW update	
<input type="button" value="Choose File"/>	No file chosen
<input type="button" value="Upload"/>	
Loaded Firmware	TST3xx-v2.12
Status	Idle
<input type="button" value="Update"/>	

To arrange the FW update, the appropriate file should be uploaded to the sensor first and after this, the button "Update" should be pressed.

8.5. Logger

The logger utilizes circular buffer in FLASH memory. When it is full, the new data overwrites the oldest one. In this manner FLASH memory stores full log all the time. There isn't a command to clear the log. Copy of full log is always available for download.

The number of records depends on how long descriptions and what kind of characters are used. In the worst case (15 bytes description with characters from the highest part of UTF-8) the number of records is about 52000. This number is enough for 36 days with records every 1 minute.

The new data can be periodically uploaded as a file to the dedicated HTTP server in time intervals – 1, 2, 3, 4, 6, 8, 12 and 24 hours. The data is sent in CSV format. The semicolon is used for a delimiter.

The first row of the log file is always header. All rows, including the header, start with record ID and time stamp.

Structure of one row (record) of the log is as follows:

ID	Time	Type of record	Inputs value	Relays	Alarm conditions
----	------	----------------	--------------	--------	------------------

- ID 32-bit unique number for every row (record).
- Time time stamp of record, in format yyyy.mm.dd, hh:mm:ss.
- Type of record following types of records are available:
 - "Time" for periodical record;
 - "Event" for record initiate by alarm condition;
 - "Type" for header record;
 - "Start" after power-up condition;
 - "Restart" after reset condition;
 - "Power Down" after power-down condition;
 - "Bad" for problematic record.
- Inputs value sensors.
- Alarm conditions show condition for every input, "1" means an active alarm.

Example of log file:

```
1131901;15.10.2015,01:02:23;Type;S11/°C;S12;S21/°C;S22;S31/°C;S32;S41/°C;S42;S51/°C;S52;S61/°C;S62;S71/°C;S72;S81/°C;S82;A1/V;A2/V;D1;D2;R1;R2;S11/°C;S12;S21/°C;S22;S31/°C;S32;S41/°C;S42;S51/°C;S52;S61/°C;S62;S71/°C;S72;S81/°C;S82;A1/V;A2/V;D1;D2;
1131902;15.10.2015,01:02:23;Time;18.250;;18.375;;18.125;;18.500;;18.188;;18.125;;18.375;;18.375;;11.352;0.065;1;0;1;0;1;1;;1;;1;;1;;1;;1;0;1;0;
1131903;15.10.2015,01:02:23;Event;18.250;;18.438;;18.125;;18.500;;18.188;;18.125;;18.313;;18.375;;11.352;0.066;0;1;0;1;1;1;;1;;1;;1;;1;1;0;0;1;
1131904;15.10.2015,01:02:24;Time;18.250;;18.438;;18.125;;18.500;;18.188;;18.125;;18.313;;18.375;;11.352;0.066;0;1;0;1;1;1;;1;;1;;1;;1;1;0;0;1;
1131905;15.10.2015,01:02:25;Time;18.250;;18.375;;18.125;;18.500;;18.188;;18.125;;18.313;;18.375;;11.352;0.066;0;1;0;1;1;1;;1;;1;;1;;1;1;0;0;1;
1131906;15.10.2015,01:02:26;Time;18.250;;18.375;;18.125;;18.500;;18.188;;18.125;;18.313;;18.313;;11.352;0.066;0;1;0;1;1;1;;1;;1;;1;;1;1;0;0;1;
1131907;15.10.2015,01:02:27;Time;18.250;;18.375;;18.125;;18.438;;18.188;;18.125;;18.313;;18.313;;11.352;0.066;0;1;0;1;1;1;;1;;1;;1;;1;1;0;0;1;
1131908;15.10.2015,01:02:27;Event;18.250;;18.375;;18.125;;18.438;;18.188;;18.125;;18.313;;18.313;;2.198;9.092;0;1;0;1;1;1;;1;;1;;1;;1;0;0;0;1;
```


9. Factory default settings

TCW210-TH can be restored to its original factory default settings in 3 different ways.

9.1. Factory default from WEB interface

If the button “Factory default” from Administration->Backup/Restore is pressed, all parameters return to factory default except Network settings.

9.2. Factory default with the reset button

If the reset button is pressed for more than 5 seconds, while the device is working, all Network settings go to factory default.

9.3. General factory default with the reset button

For factory default reset of all parameters following steps should be executed:

- Press and hold the RESET button, then turn on the power supply;
- Yellow LED shines and red LED blinks about 5 times on a second;
- After about 5 seconds red LED will turn off, the button can be released;
- Yellow LED flashes on 1 second and red LED shines – the device is in working mode, with factory default settings.



The factory default settings are:

Username	admin
Password	admin
IP Address	192.168.1.2
Subnet Mask	255.255.255.0
Default Gateway	192.168.1.1
SNMPConfiguration	disabled
readCommunity	public
writeCommunity	private

10. Environment information

This equipment is intended for use in a Pollution Degree 2 environment, at altitudes up to 2000 meters. When the controller is a part of a system, the other elements of the system shall comply with the EMC requirements and shall be intended for use in the same ambient conditions.

11. Safety

This device must not be used for medical, life-saving purposes or for any purpose where its failure could cause serious injury or the loss of life.

To reduce the risk of fire, only flexible stranded wire, with cross section 0.5mm² or larger for wiring of digital and analog inputs and relay output of the device should be used.

To avoid electric shock and fire hazard, do not expose this product to liquids, rain, or moisture. Objects filled with liquids, such as vases, should not be placed on this device.

There is a risk of overheating (damage) of the controller, if recommended free spaces to adjacent devices are not ensured. The joint part with external component shall have space for attachment/removal of the cable after installation.

Teracom does not guarantee successful operation of the product if the product was used under conditions deviating from the product specifications.

To ensure that the device works correctly follow the steps below:

- ensure that the device is installed correctly, refer to this user manual;
- log in to the devices via a browser program;
- make proper setup;
- install sensor TSH1XX or TST1XX on the 1-Wire bus;
- install sensor TSH3XX or TST3XX on the RS-485 bus;
- go to “Monitoring page” of WEB interface – proper parameters value should be displayed at the same time flashing “STS” led should indicate the proper operation.

If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Teracom Ltd. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

12. Maintenance

Upon completion of any service or repairs to the device or once per year, a safety check must be performed to determine that this product is in proper operating condition.

Clean the device only with dry cloth. Do not use a liquid cleaner or an aerosol cleaner. Do not use a magnetic/static cleaning device (dust remover) or any kind of abrasive materials to clean the device.

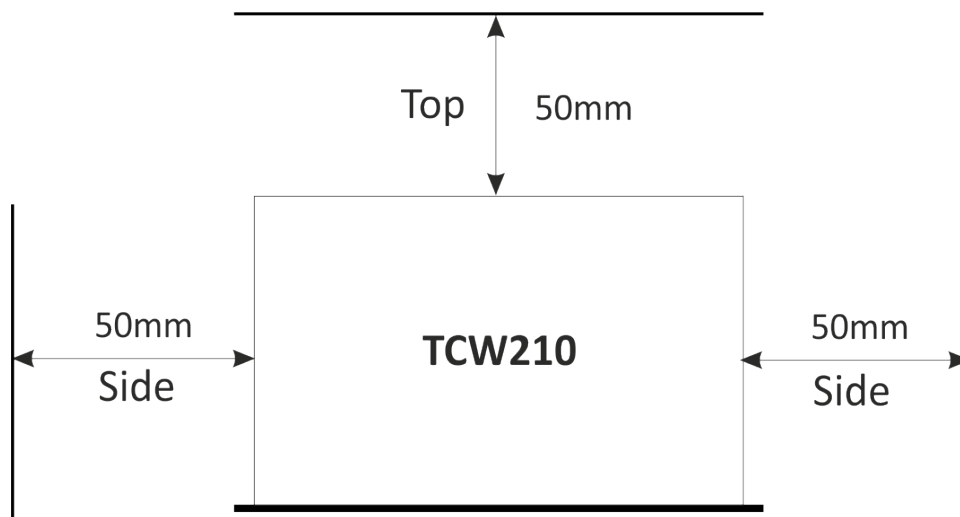


Fig.1